



# Machine Learning for Bioinformatics & Systems Biology

## 0. On-line background

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*Some material courtesy of Robert Duin, David Tax & Dick de Ridder*

# Modelling .... Learning from examples



# Machine learning

- Wikipedia:
  - "the scientific study of **algorithms** and **statistical models** that computer systems use to perform a specific task without using explicit instructions, relying on **patterns** and **inference** instead ... Machine learning algorithms build a **mathematical model** based on **sample data**, known as "**training data**", in order to make **predictions** or **decisions** without being explicitly programmed to perform the task."
- Christopher M. Bishop:
  - "**Pattern recognition** has its origins in **engineering**, whereas **machine learning** grew out of **computer science**. However, these ... can be viewed as two facets of the **same field**"

# Machine learning (2)

- The construction of **approximate, generalizing (predictive) models** by **learning from examples**, for problems for which *no full physical model is known (yet)*
- Focus in this course will be on **classification** and **statistical machine learning**, not (so much) on *regression, structural/syntactic* pattern recognition and *reinforcement learning*.

- Related areas
  - Applied statistics
  - Pattern recognition
  - Artificial intelligence
  - Computer vision
  - Data mining

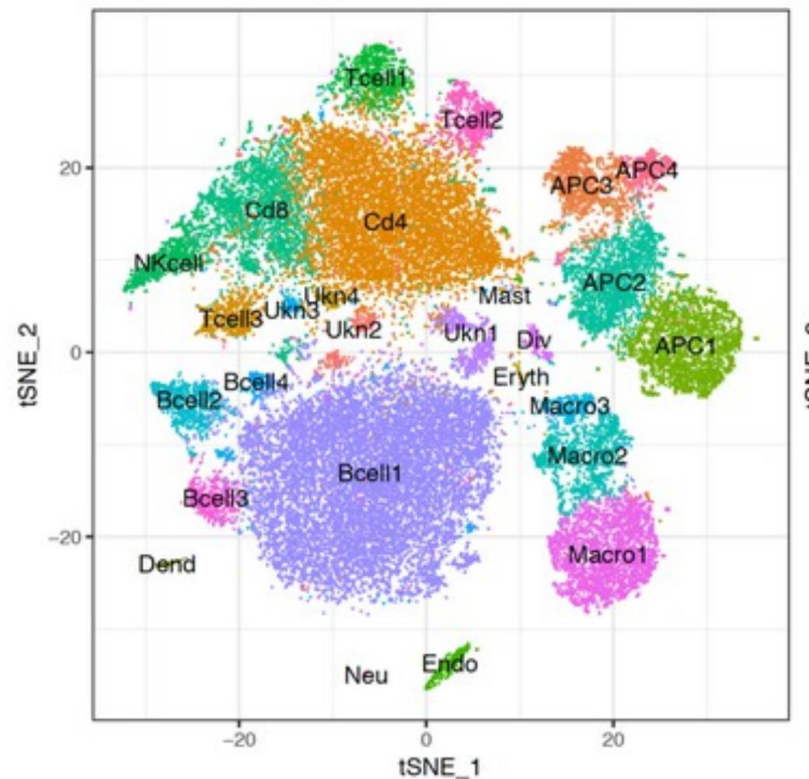


# Machine learning (3)

- Examples:
  - Computer vision: license plate reading, people counting, face detection, smart cameras, ...
  - Signal processing: thermostat, speech/speaker recognition, ...
  - Information retrieval: Google, Amazon, automated translation, ...
  - Biometrics: fingerprint recognition, iris scan, signature verification...
  - Defensive: friend-or-foe recognition, target tracking, ...
  - Medicine: interpreting scans, diagnostic systems, ...

# Machine learning (4)

- Bioinformatics:
  - Gene (function) prediction, SNP prioritization, ...
  - Diagnosis/prognosis, biomarker discovery, ...
  - Network inference: PPI, metabolic networks, ...
  - Cell-type identification, ...
  - Etc.



# Goal

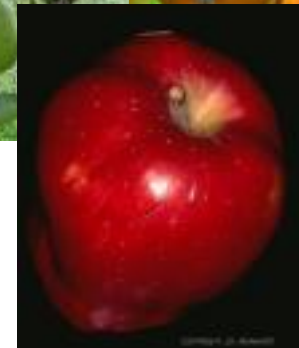
- After having followed this course, the student has a good understanding of **a wide range of machine learning techniques** and is able to **recognize what method is most applicable** to data analysis problems (s)he encounters in bioinformatics and systems biology applications.
- Many problems are in fact machine learning problems!

# Machine learning (5)

- Finding structure in data
  - Outlier/anomaly detection
  - Clustering
  - Dimensionality reduction, selecting useful (combinations of) features
  - Regression
  - Classification
  - ...
- All aimed at *generalisation*:  
**making a prediction for data you have not yet seen**

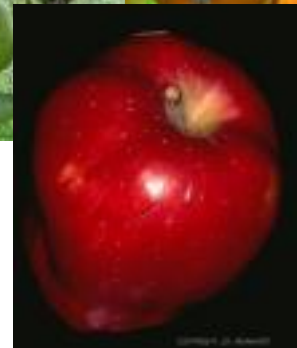
# Clustering

- Can we find natural groups in the data?
- E.g. red vs green fruit



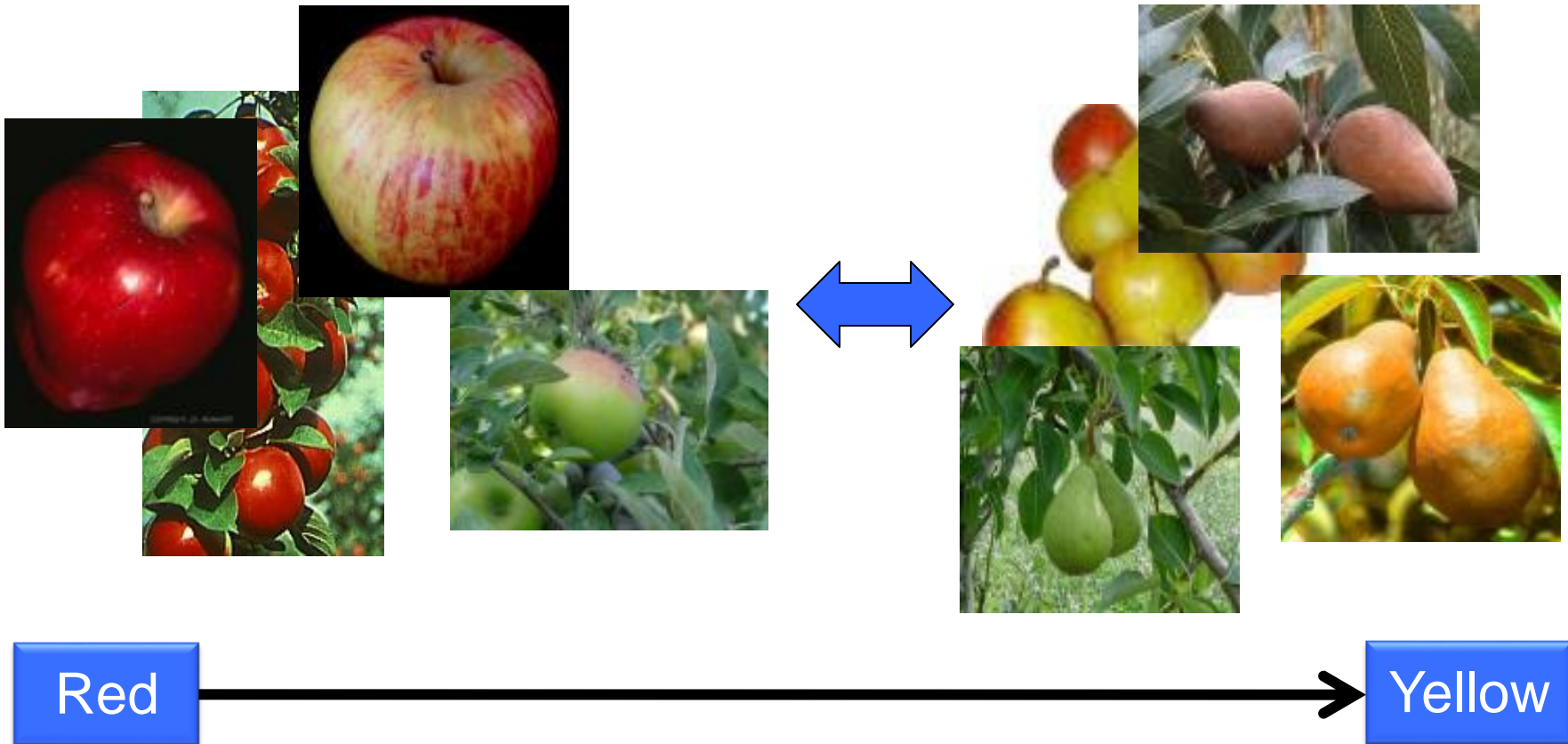
# Outlier detection

- Can we find strange objects?



# Dimensionality reduction

- Can we find predictive measurements?

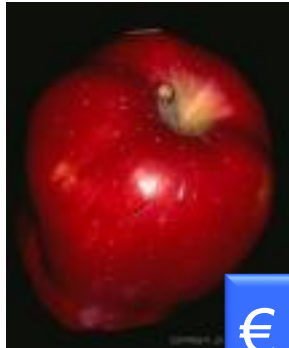


# Regression

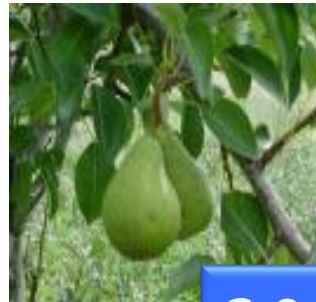
- Can we predict real-valued outputs?



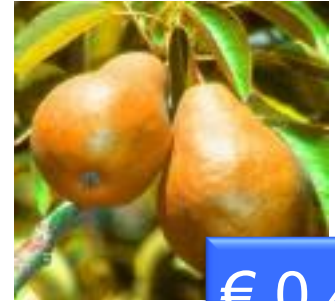
€ 0.25



€ 0.30



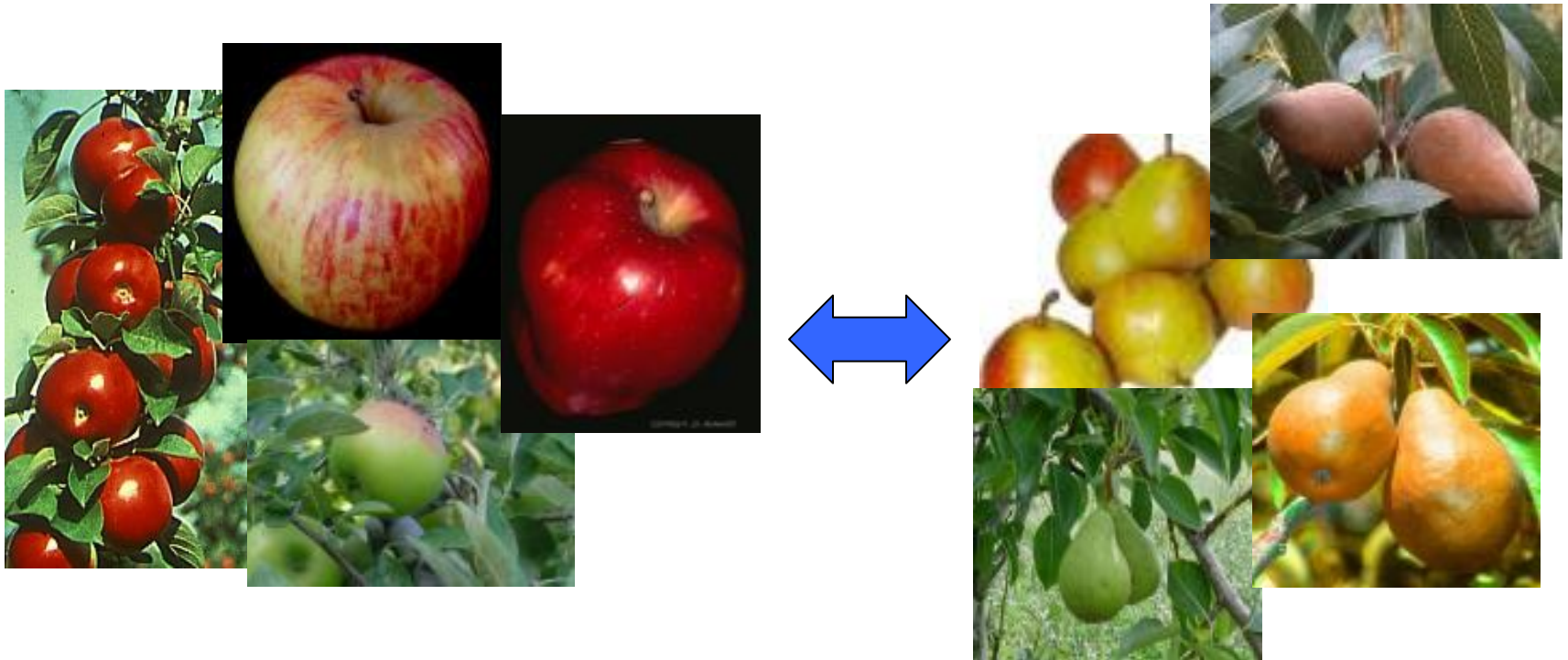
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€ 0.45

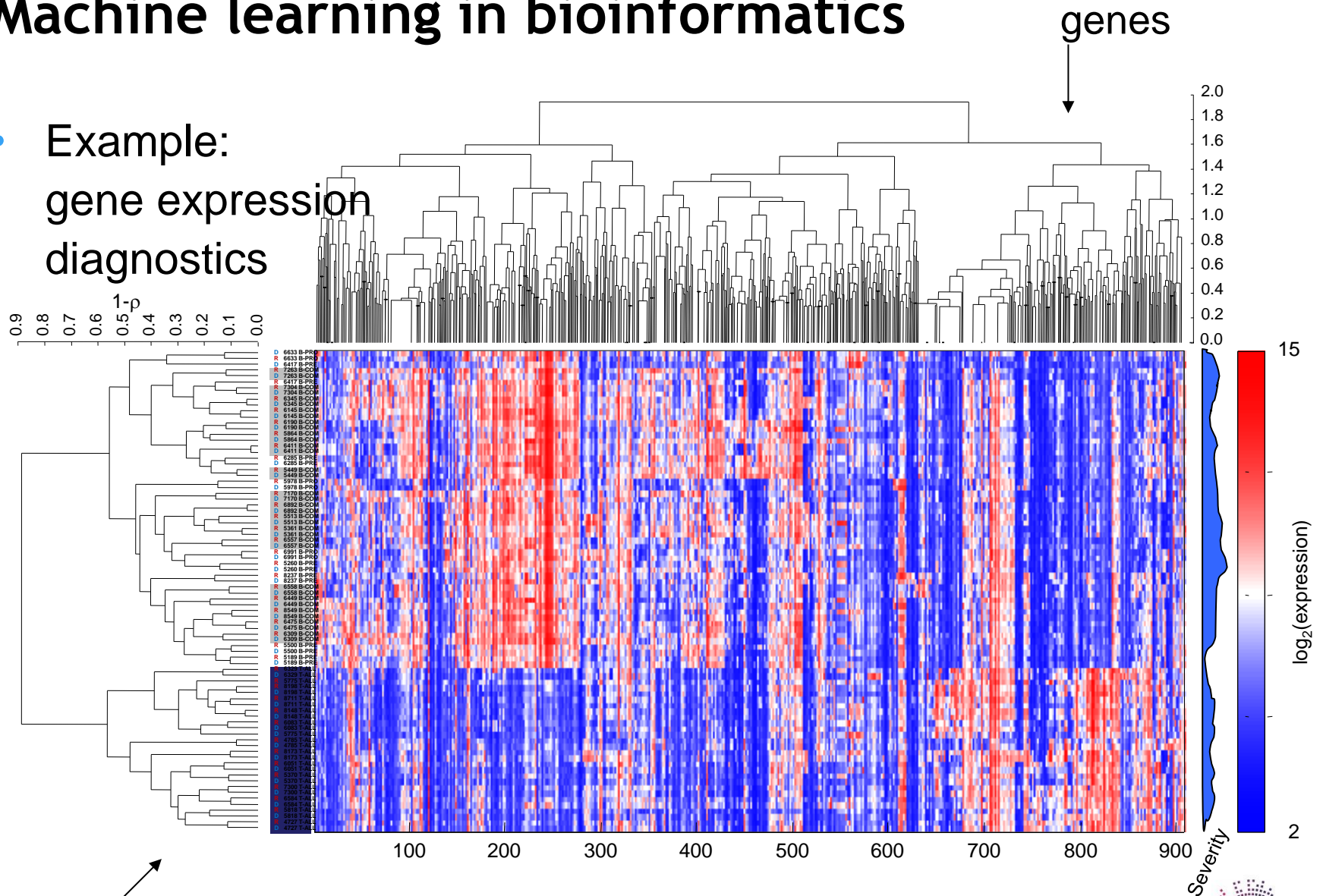
# Classification

- Can we distinguish apples from pears?



# Machine learning in bioinformatics

- Example:  
gene expression  
diagnostics

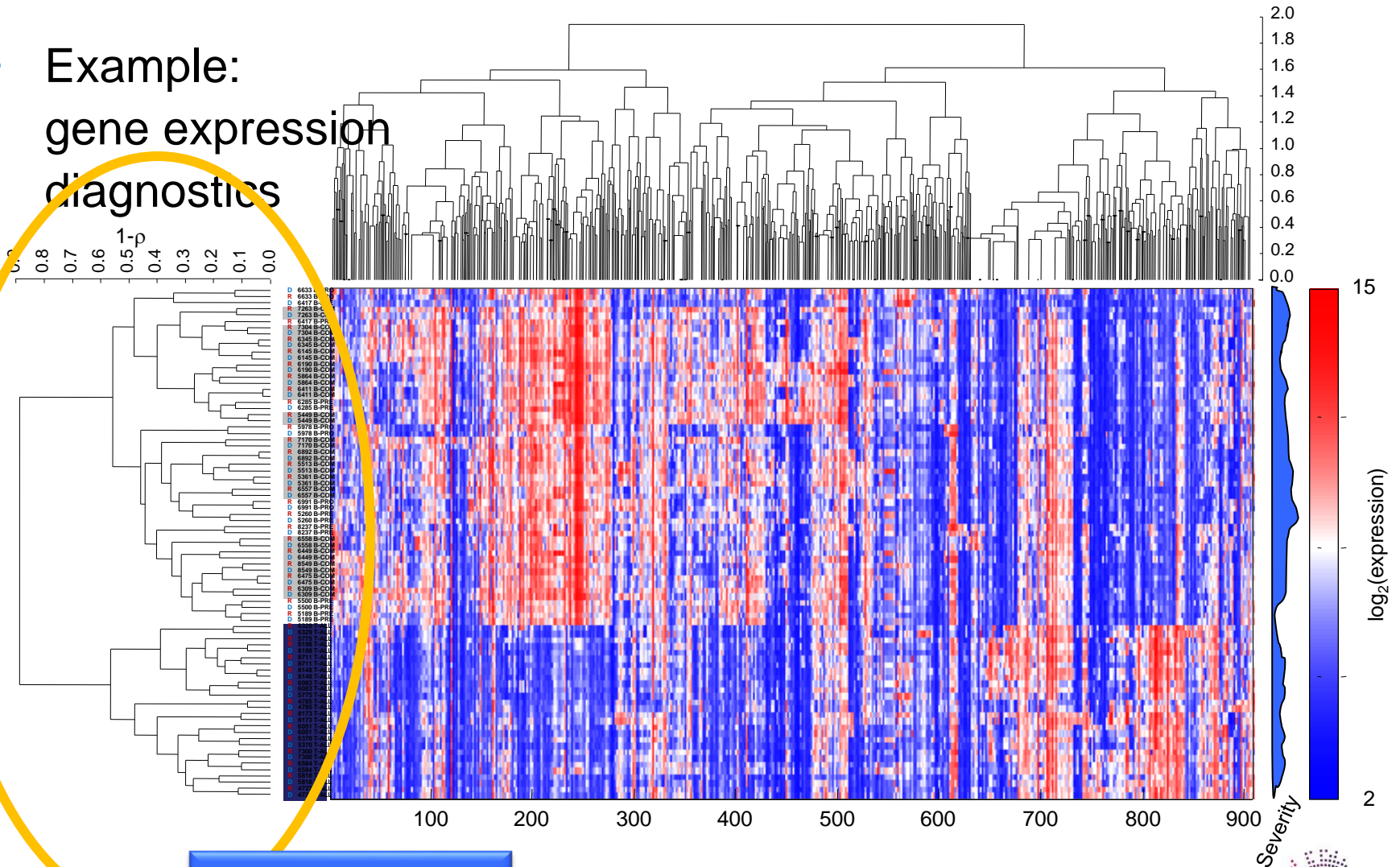


samples

diagnosis/relapse in childhood leukemia

# Machine learning in bioinformatics

- Example:  
gene expression  
diagnostics



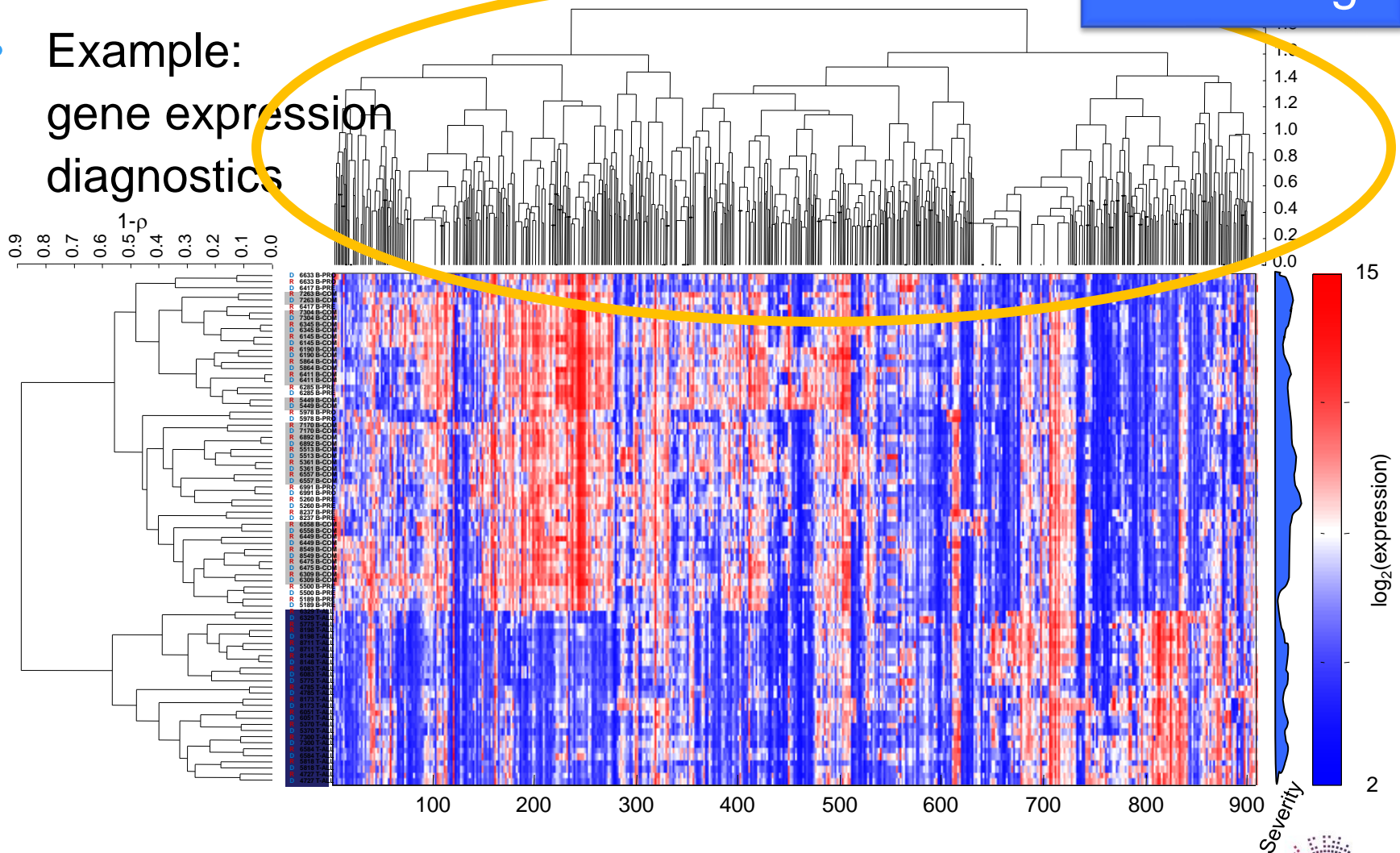
# Clustering

*Clustering of patients: similar subtypes of disease*

# Machine learning in bioinformatics

Clustering

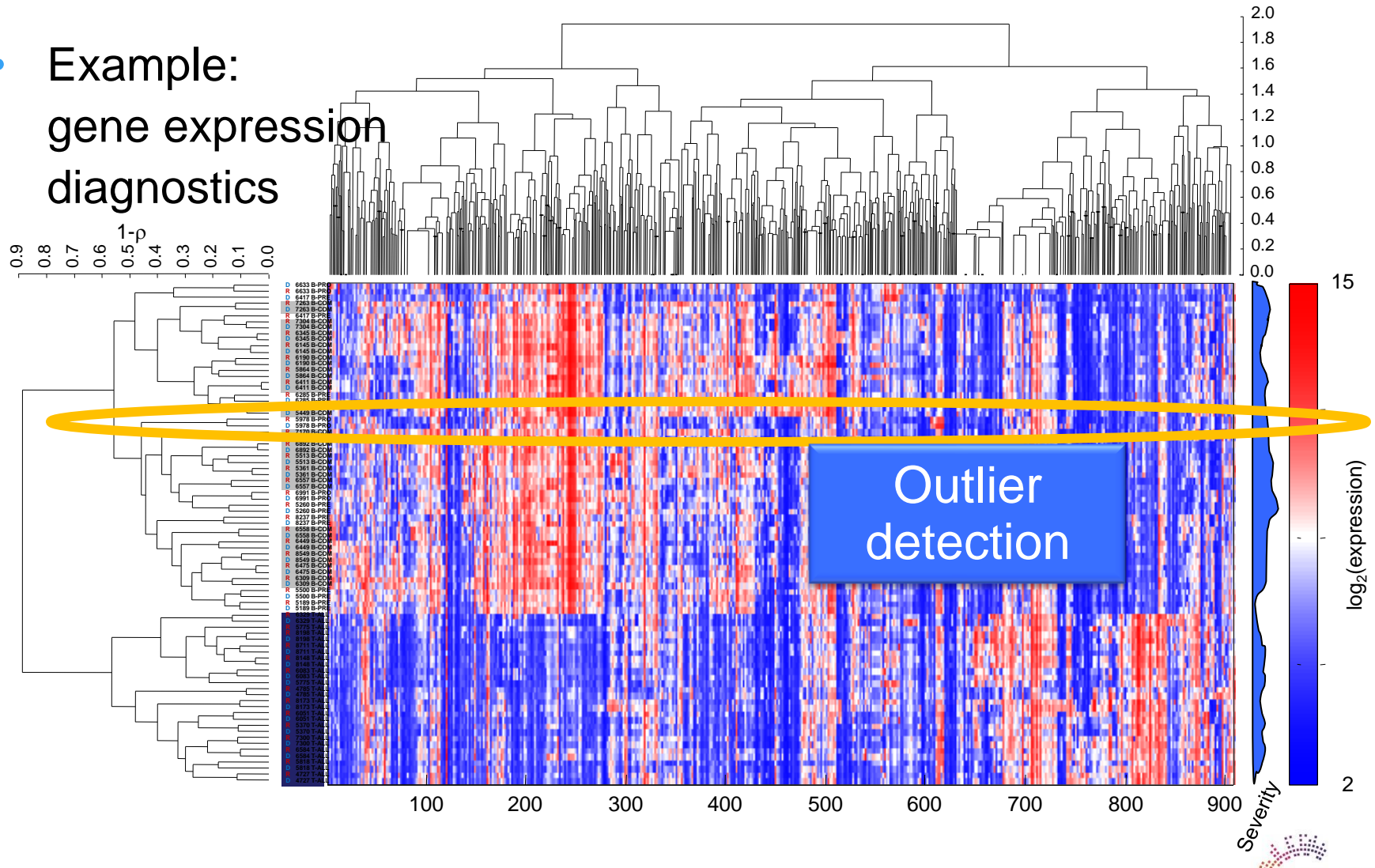
- Example:  
gene expression  
diagnostics



Clustering of genes: similar 'disruptive' processes

# Machine learning in bioinformatics

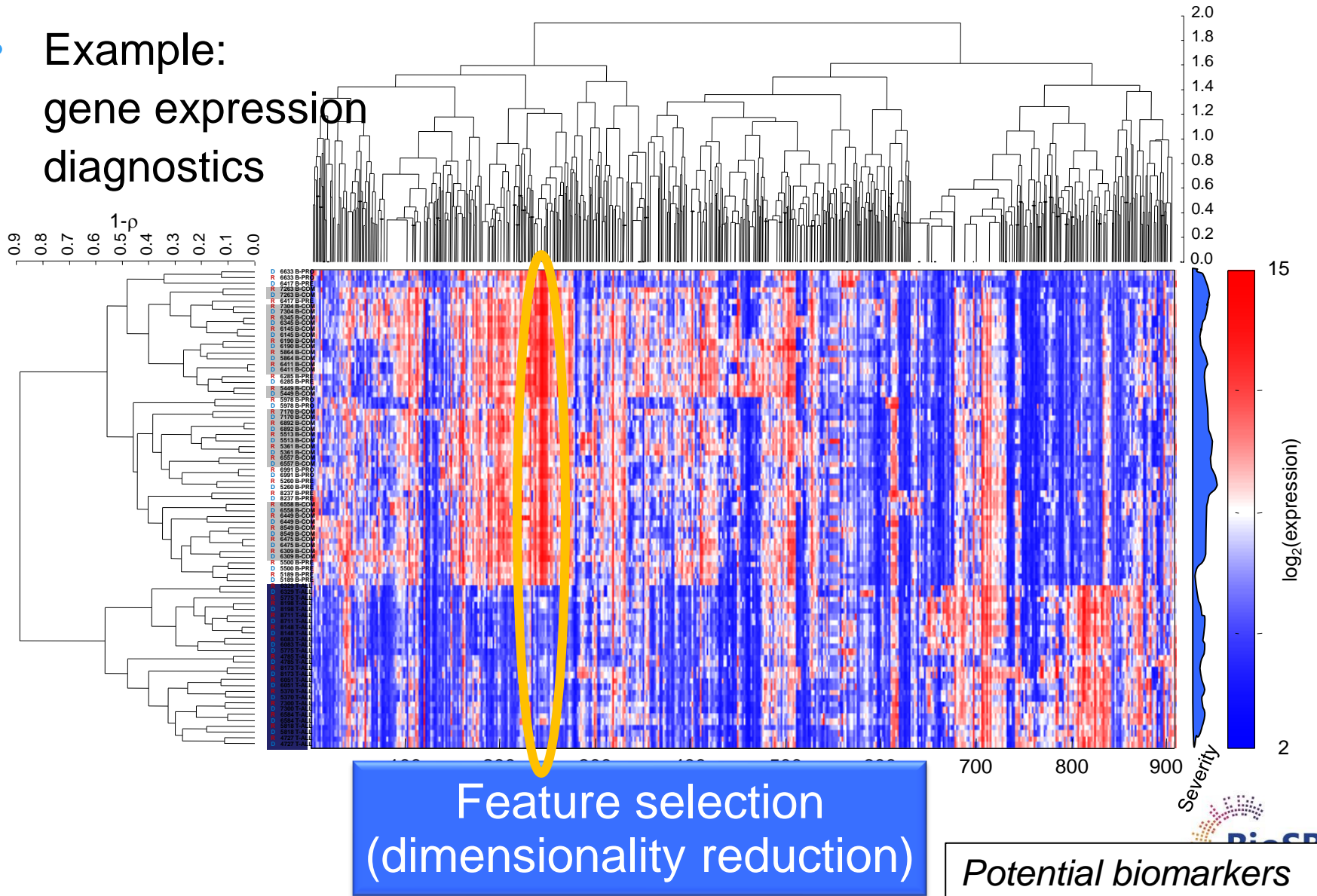
- Example:  
gene expression  
diagnostics



*Technical error / rare patient-rare genetic background*

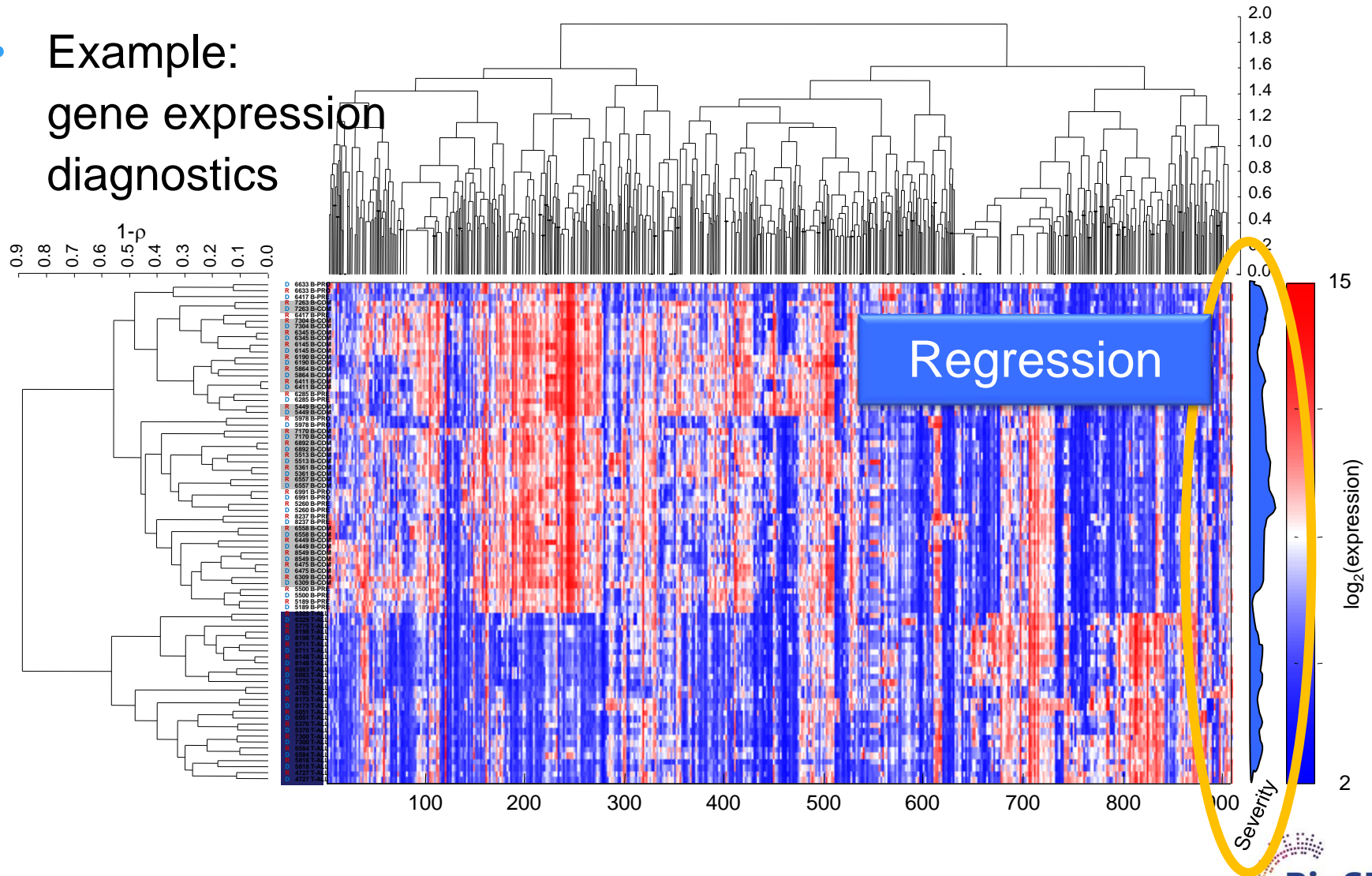
# Machine learning in bioinformatics

- Example:  
gene expression  
diagnostics



# Machine learning in bioinformatics

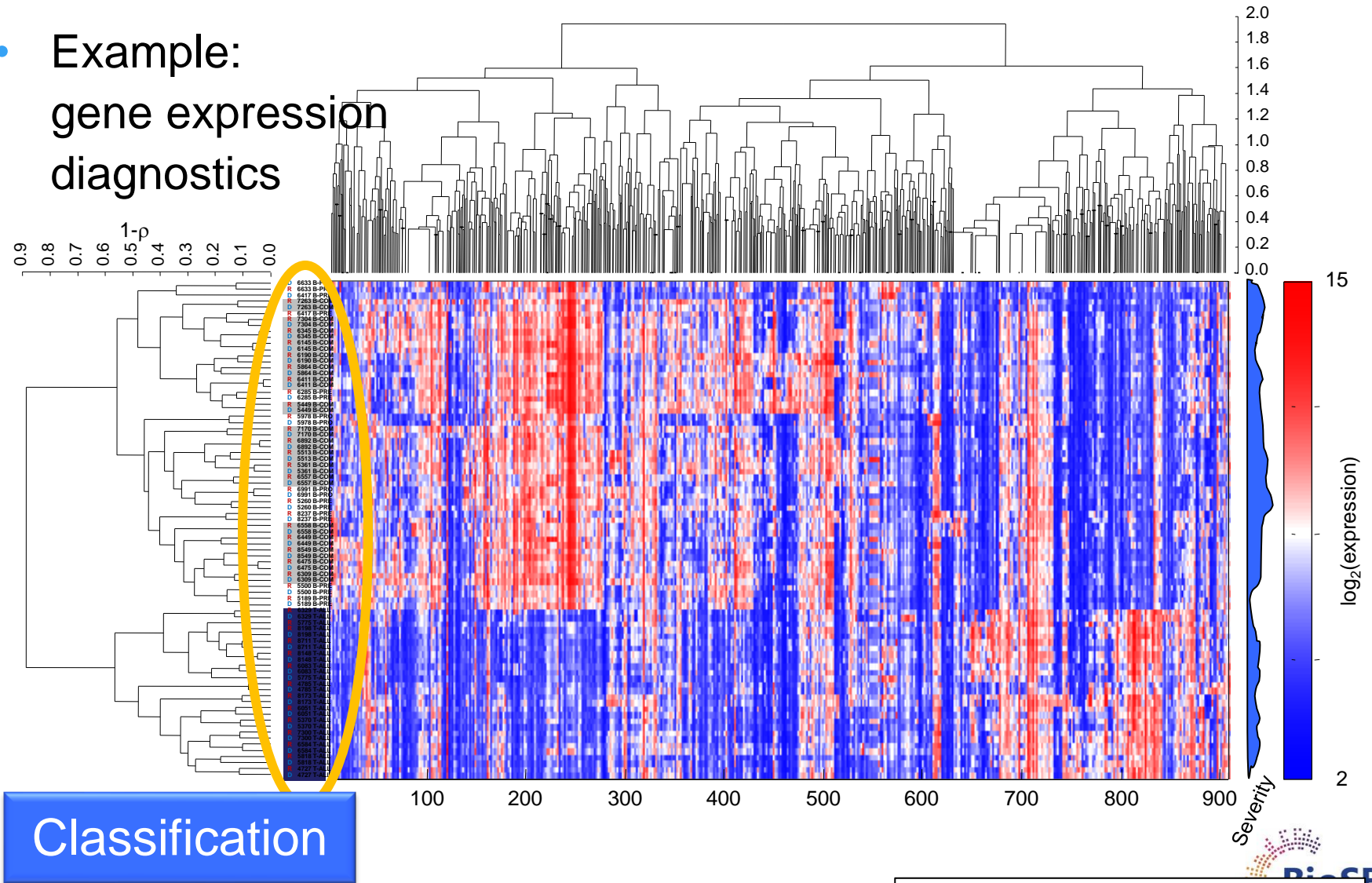
- Example:  
gene expression  
diagnostics



*E.g. Predicting survival time*

# Machine learning in bioinformatics

- Example:  
gene expression  
diagnostics



*E.g. Predicting metastasis*

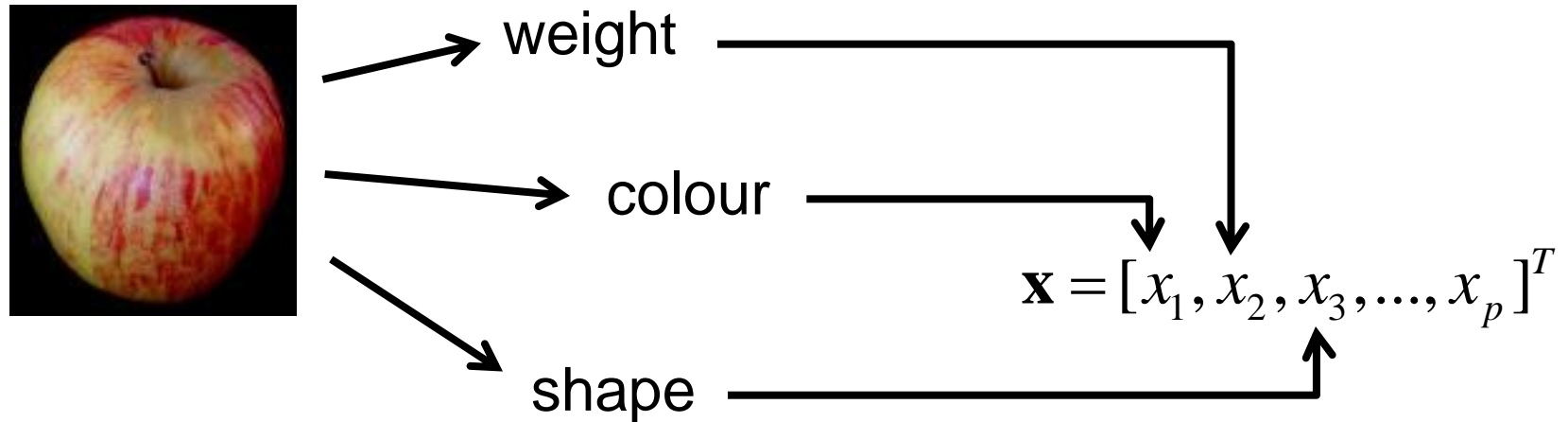
# Machine learning in bioinformatics (2)

- Tools applicable to any type of biological data
- Examples:
  - Protein sequence data:
    - Clustering: finding orthologous groups
    - Classification: prediction of EC number, subcellular localization, ...
    - Regression: predicting secondary structure
  - TF binding data (ChIP):
    - Clustering: finding functional gene groups
    - Classification: predicting gene annotation
    - Regression: finding cis-regulatory modules
  - ...

# Terminology

# Measurements and features

- To automate these tasks, we have to find a mathematical *representation* of objects
- Objects are usually represented by *features*, i.e. sets of useful *measurements* obtained from some *sensors*



# Measurements and features (2)

- This course assumes measurements as given, i.e. sensor accuracy etc. are not *explicitly* modeled
- However,
  - in general measurements will never be perfect
  - objects within a class will vary intrinsically
- Hence, we need statistics to model all variation

*This is important!*

*If we know everything and there is no noise, you'll need different algorithms/models*

# Datasets

- A *dataset* is a set of measurements on many objects
- For clustering:

Object	Weight	Colour
Apple #1	25	36
Apple #2	20	34
Apple #3	35	40
Pear #1	35	55
Pear #2	37	55
Pear #3	40	57
Pear #4	36	41

# Datasets

- A *dataset* is a set of measurements on many objects
- For regression:

Object	Weight	Colour	Price
Apple #1	25	36	0.21
Apple #2	20	34	0.17
Apple #3	35	40	0.33
Pear #1	35	55	0.41
Pear #2	37	55	0.26
Pear #3	40	57	0.35
Pear #4	36	41	0.29

# Datasets

- A *dataset* is a set of measurements on many objects
- For classification:

Object	Weight	Colour	Label
Apple #1	25	36	A
Apple #2	20	34	A
Apple #3	35	40	A
Pear #1	35	55	P
Pear #2	37	55	P
Pear #3	40	57	P
Pear #4	36	41	P

# Datasets

- A *dataset* is a set of measurements on many objects
- For classification:

The diagram shows a table with four columns: Object, Weight, Colour, and Label. The rows represent individual objects: Apple #1, Apple #2, Apple #3, Pear #1, Pear #2, Pear #3, and Pear #4. Annotations include: a large orange circle around the entire table labeled 'dataset'; a red oval around the 'Object' column labeled 'object'; a green oval around the 'Colour' column labeled 'feature'; a blue oval around the 'Label' column labeled 'labels'; and a red circle around the value '36' in the 'Weight' column of the 'Pear #4' row, with the word 'measurement' in red text below it.

Object	Weight	Colour	Label
Apple #1	25	36	A
Apple #2	20	34	A
Apple #3	35	40	A
Pear #1	35	55	P
Pear #2	37	55	P
Pear #3	40	57	P
Pear #4	36	41	P

object

dataset

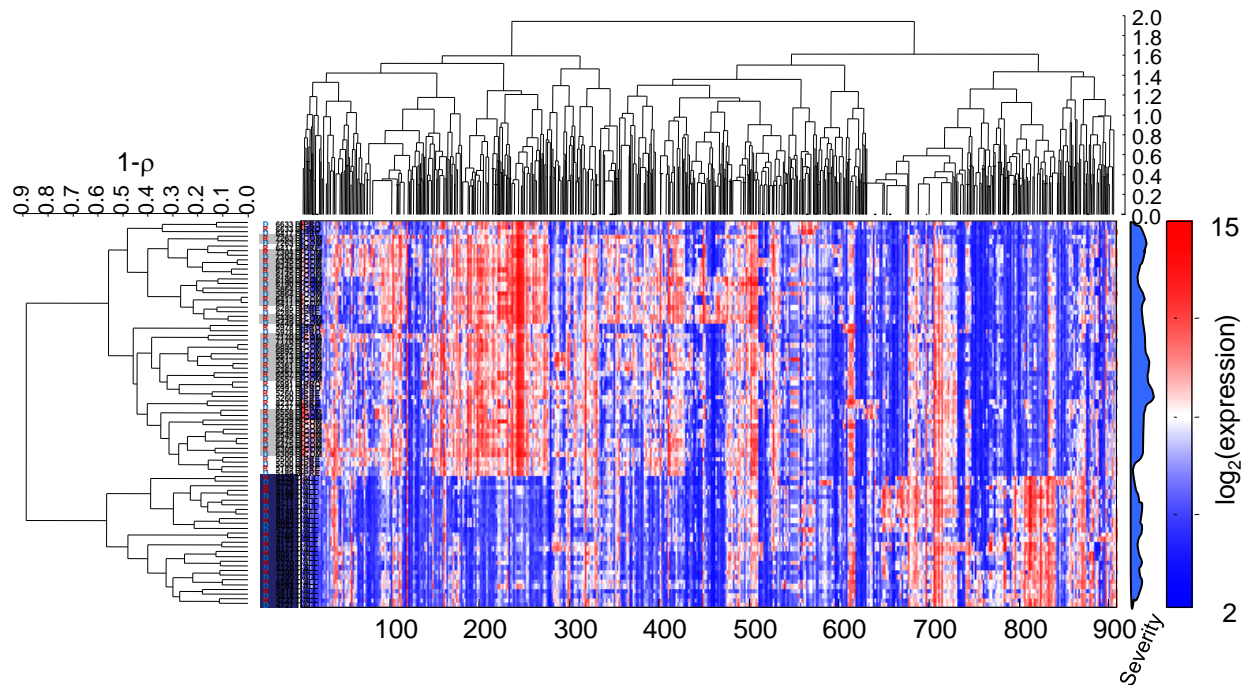
measurement

feature

labels

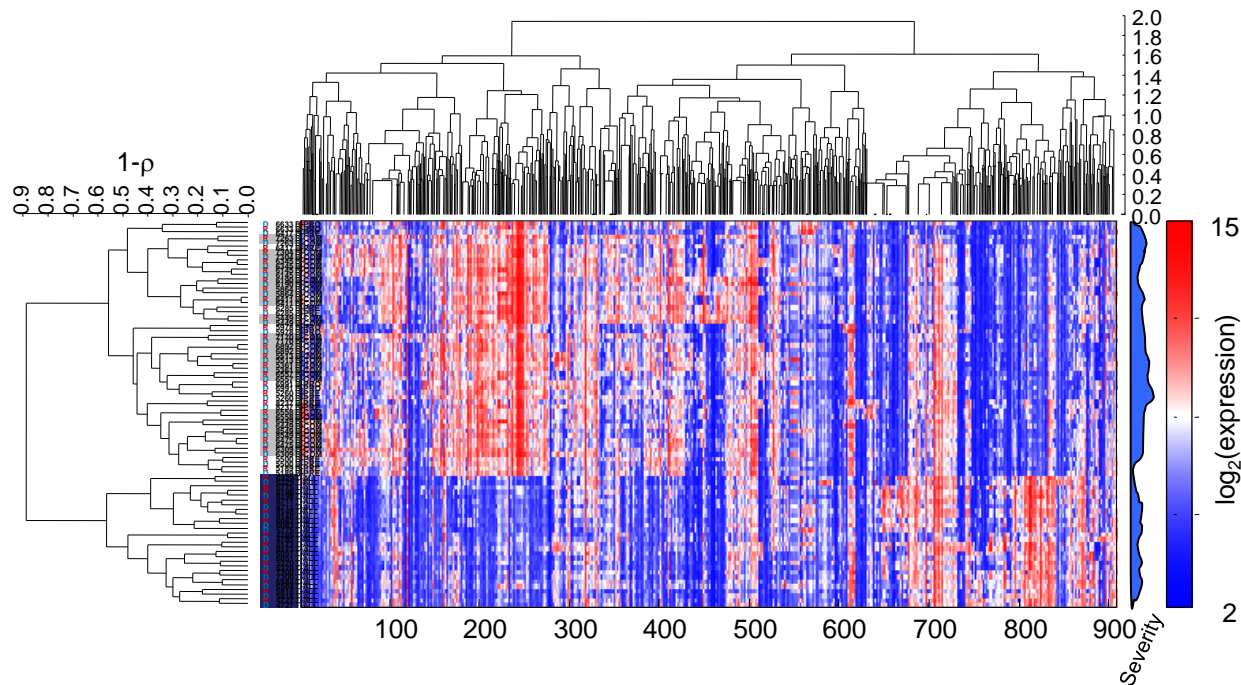
# Datasets (2)

- What objects, labels/targets and features are depends on the problem...
- Gene expression-based diagnostics:
  - object: patient
  - feature: gene expression, copy number, mutational pattern, ....
  - label: relapse; regressor/dependent variable: survival time



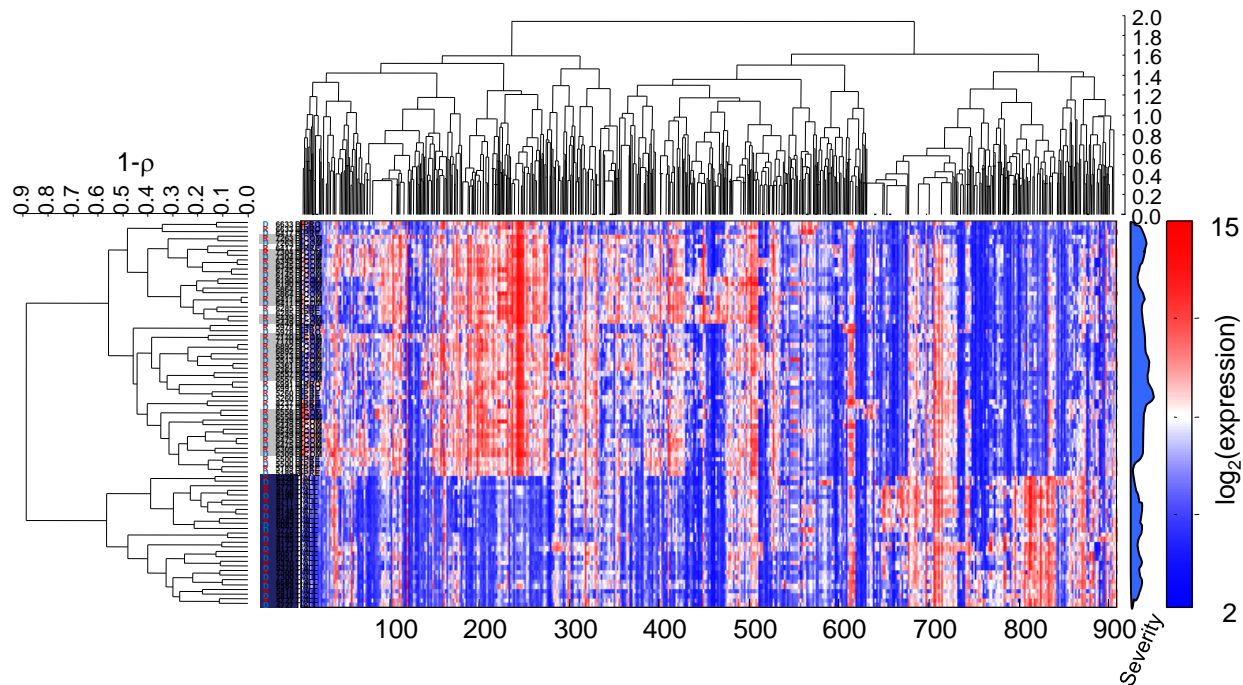
# Datasets (2)

- What objects, labels/targets and features are depends on the problem...
- Protein-protein interactions:
  - object: protein PAIR
  - feature: gene expression correlation, difference in annotation, ...
  - label: complex or not; regressor/dependent variable: binding strength



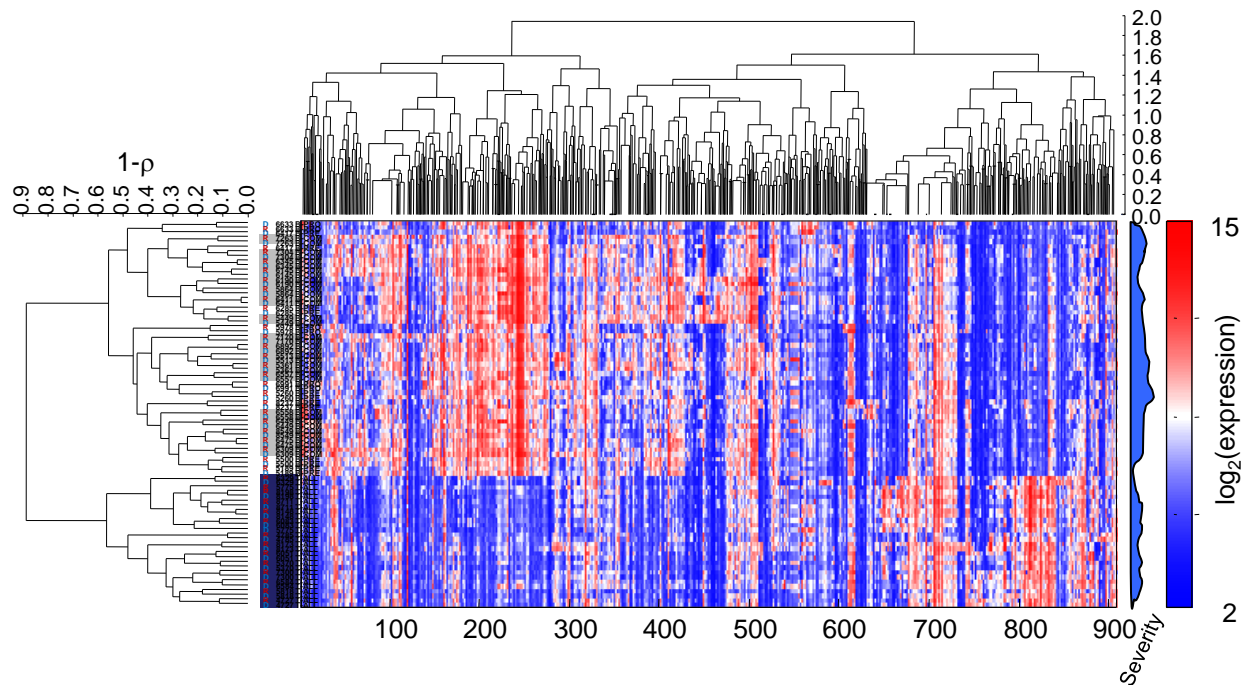
# Datasets (2)

- What objects, labels/targets and features are depends on the problem...
- Gene prediction:
  - object: gene
  - feature: sequence (representation), conservation of sequence, ...
  - label: gene or not; regressor/dependent variable: conservation



# Datasets (2)

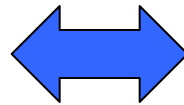
- What objects, labels/targets and features are depends on the problem...
- TFBS detection:
  - object: location on genome
  - feature: ChIP-seq, sequence features, distance to TSS ...
  - label: TFBS or not; regressor/dependent variable: specificity



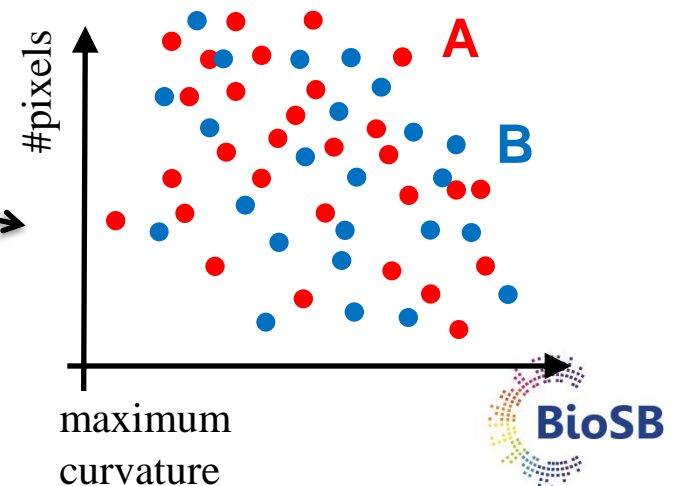
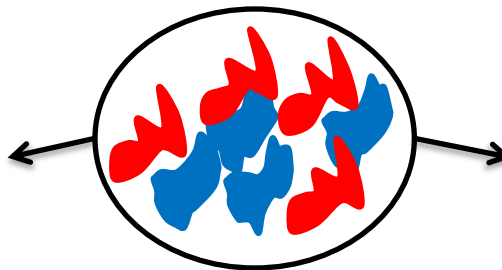
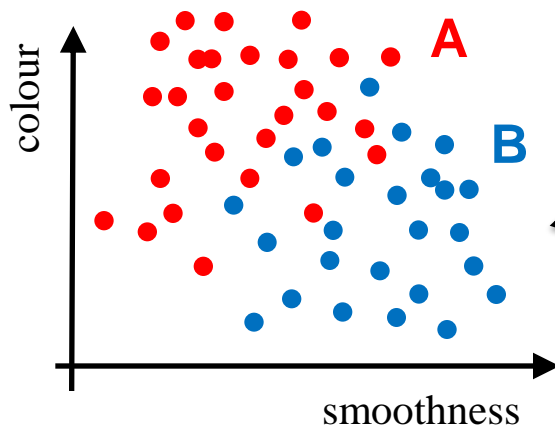
# Measurements and features (3)

- Problems

- simple
- knowledge present
- a few good features
- almost separable classes (classification) or a linear relation (regression)



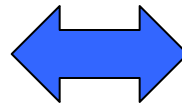
- complex
- lack of knowledge
- many poor features
- overlapping classes (classification) or highly non-linear relation (regression)



# Measurements and features (3)

- Problems

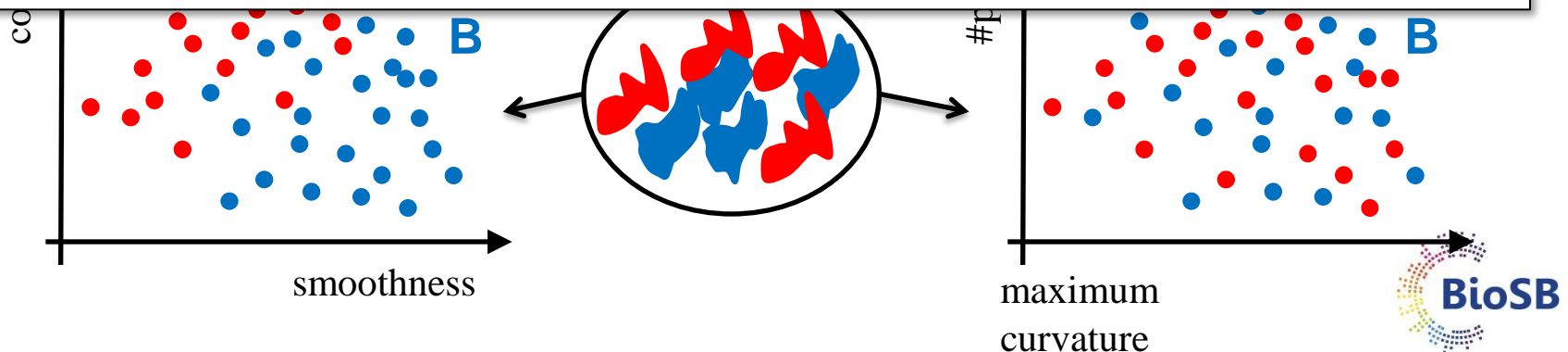
- simple
- knowledge present
- a few good features



- complex
- lack of knowledge
- many poor features
- overlapping classes

Features (object representations) are important!

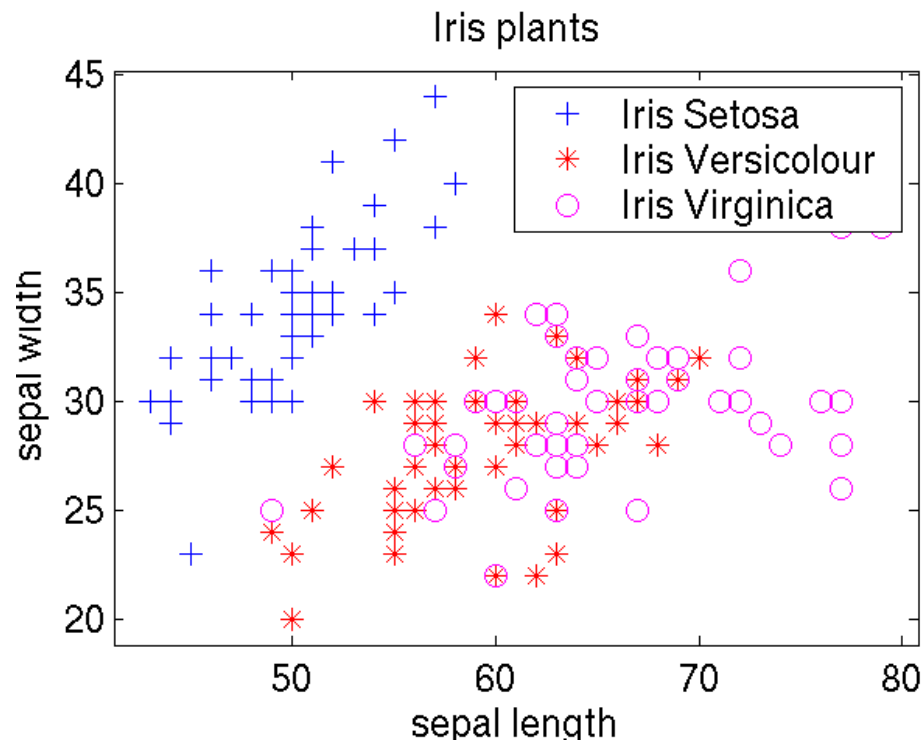
We don't deal too much with which features are measured, although we will touch upon derived features (Day 4: kernels) and learning features (Day 4: neural networks)



# Feature space

- We can interpret objects as vectors in a vector space

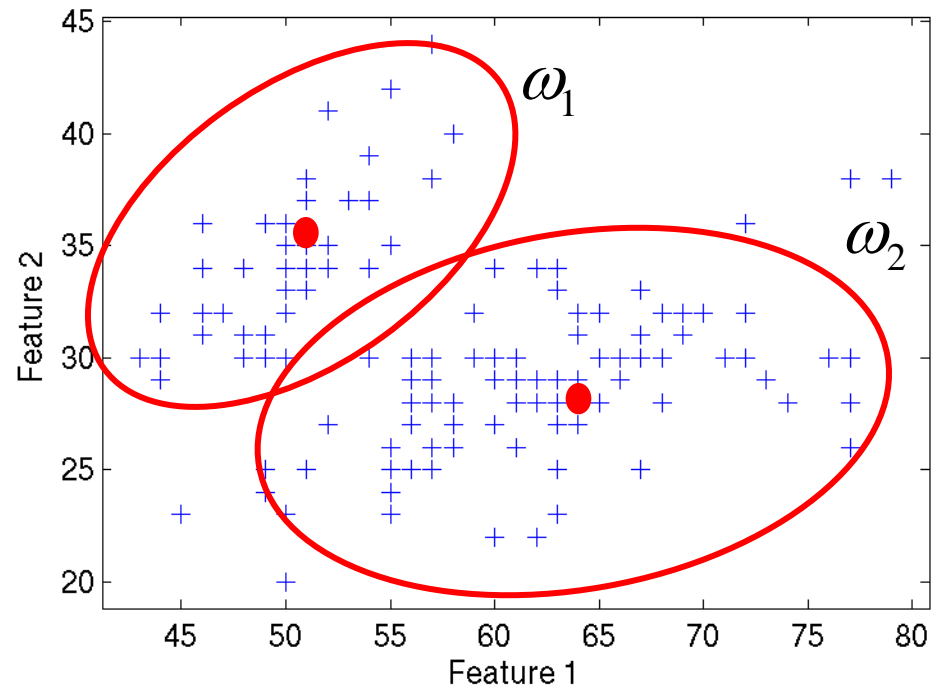
$$\mathbf{x} = [x_1, x_2, x_3, \dots, x_p]^T$$



Iris flower dataset, introduced by **Ronald Fisher (famous statistician)** in 1936 as an example of discriminant analysis

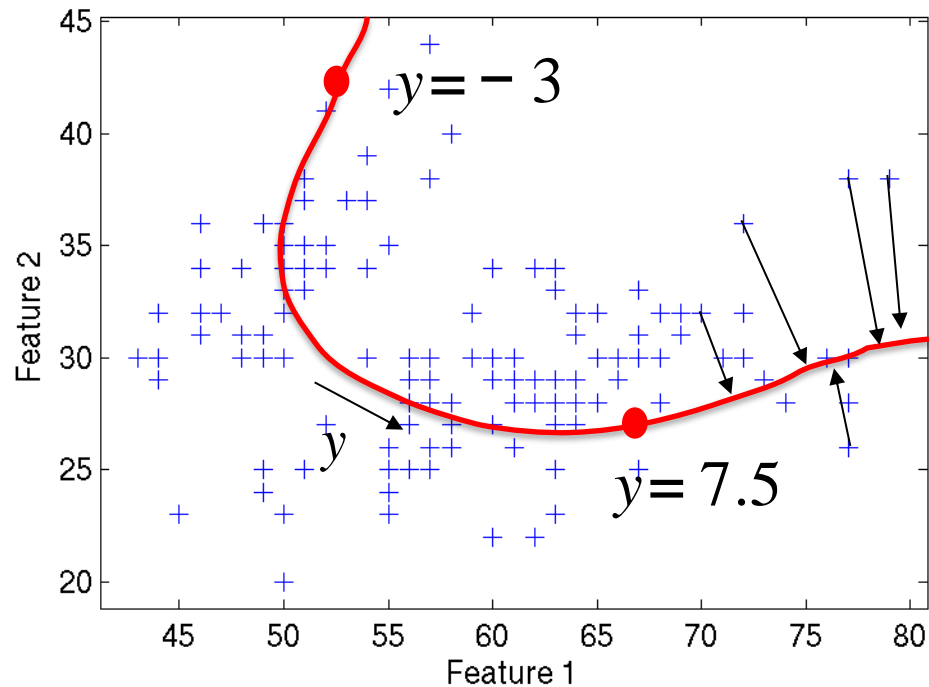
# Clustering

- Given unlabeled data  $x$ ,  
find labels  $\omega$  for natural groups in the data



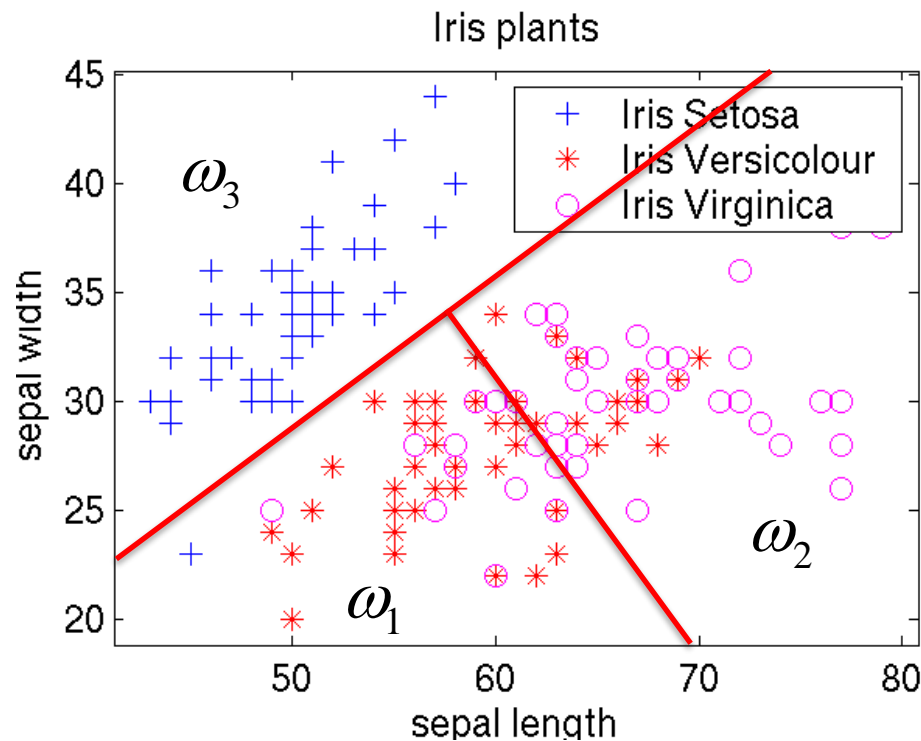
# Dimensionality reduction

- Given unlabeled data  $x$ ,  
map it to a lower dimensional feature vector  $y$



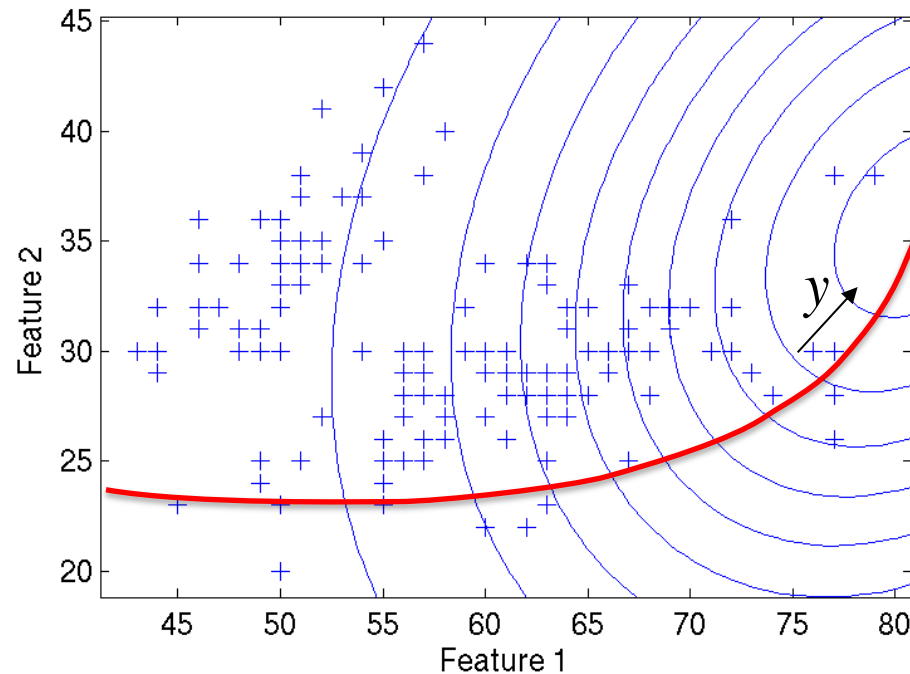
# Classification

- Given labeled data  $x$ ,  
assign each point in feature space to a class  $\omega_i$   
(in effect partitioning the feature space)



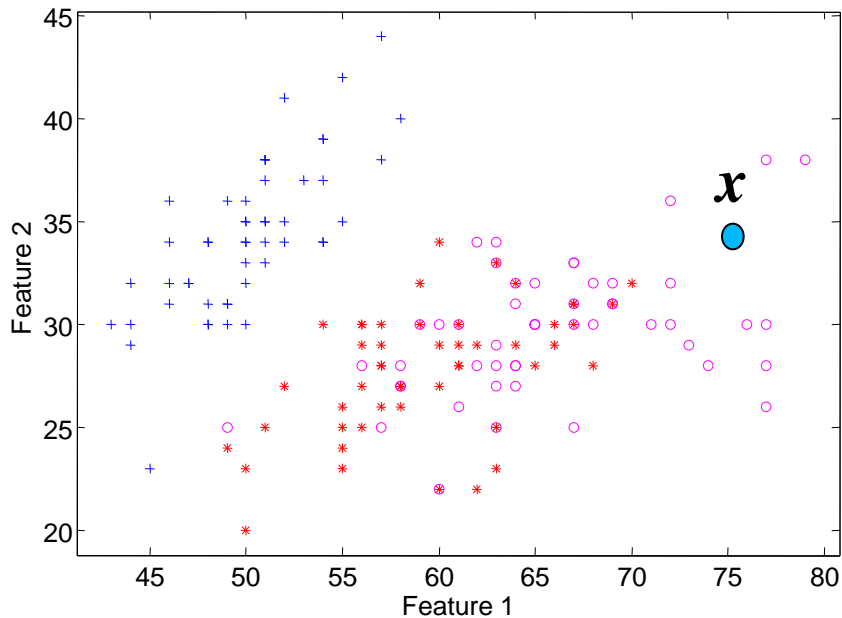
# Regression

- Given labeled data  $x$ ,  
assign each point in feature space a real-valued output  $y$



# General model

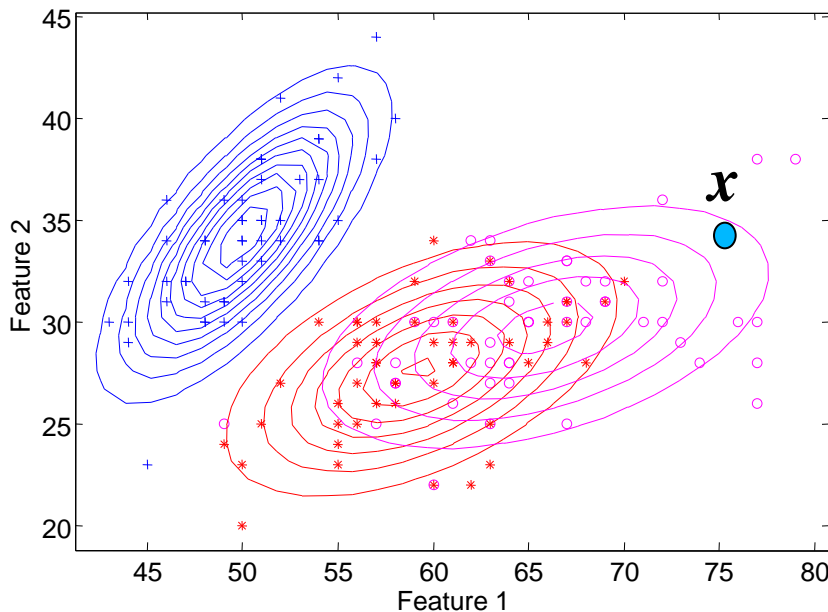
- Construct a model  $f(\mathbf{x})$  that outputs  $\omega$  or  $y$
- This model should be fit to the data



$$f(\mathbf{x}) = \omega \text{ or } f(\mathbf{x}) = y$$

# General model (2)

- Construct a model  $f(\mathbf{x})$  that outputs  $\omega$  or  $y$
- This model should be fit to the data
- Ideally, we know  $p(y | \mathbf{x})$  or  $p(\omega | \mathbf{x})$  over the entire feature space



$$p(y | \mathbf{x})$$

or

$$p(\omega | \mathbf{x})$$



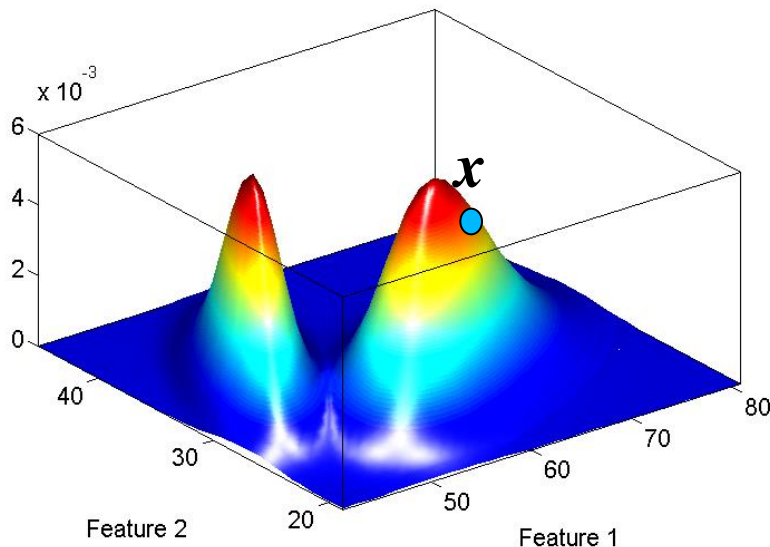
$$f(\mathbf{x}) = \omega \text{ or } f(\mathbf{x}) = y$$

*if we know the probability distributions, we can make the most informed decision*



# General model (3)

- Construct a model  $f(\mathbf{x})$  that outputs  $\omega$  or  $y$
- This model should be fit to the data
- Ideally, we know  $p(y | \mathbf{x})$  or  $p(\omega | \mathbf{x})$  over the entire feature space



$p(y | \mathbf{x})$   
or  
 $p(\omega | \mathbf{x})$



$f(\mathbf{x}) = \omega$  or  $f(\mathbf{x}) = y$

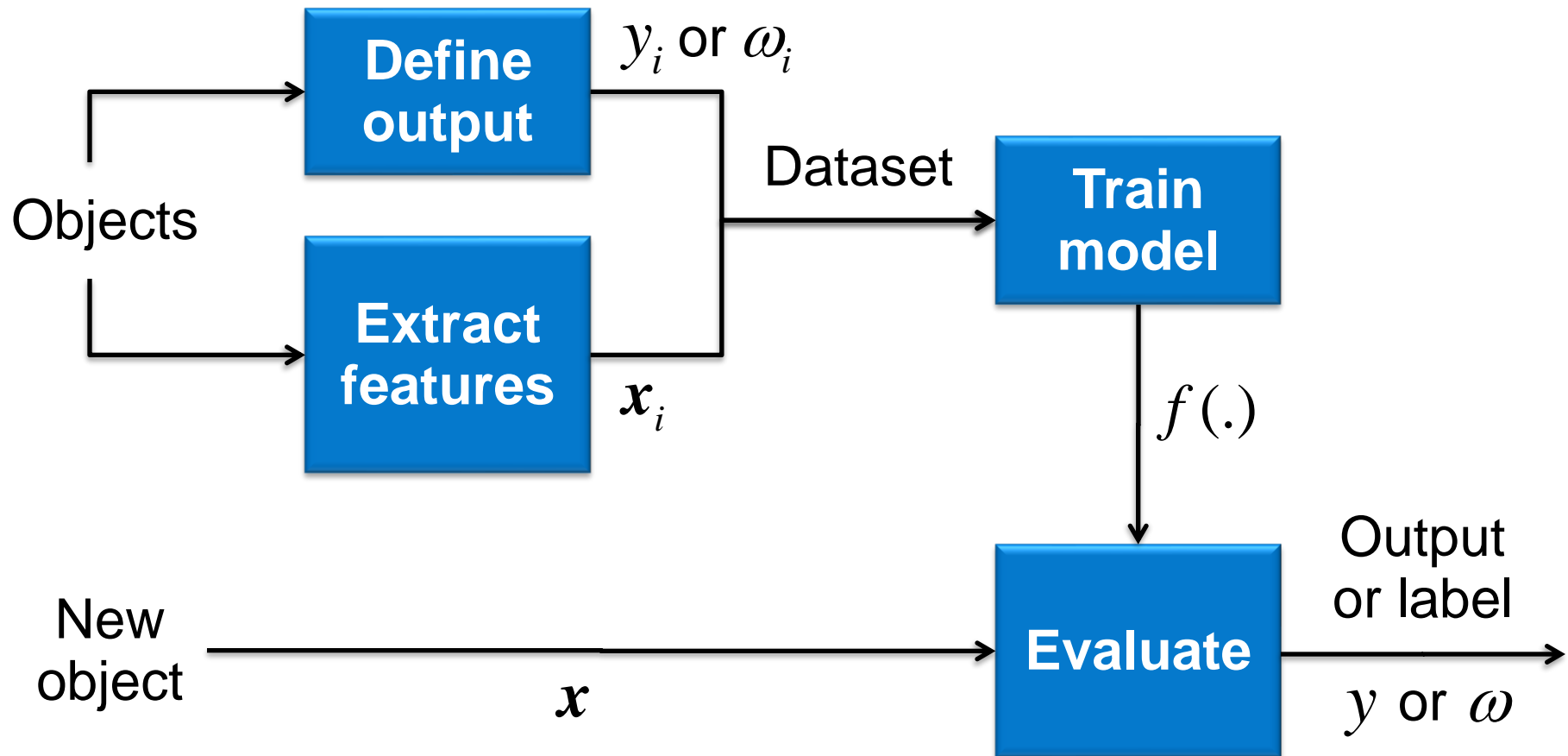
*if we know the probability distributions, we can make the most informed decision*



# General model (4)

- Clustering: find cluster labels  $\omega$  given object  $x$   
fit model using dataset  $\{x_i\}$   $p(\omega | x)$
- Dimensionality reduction: find mapping  $y$  given object  $x$   
fit model using dataset  $\{x_i\}$   $p(y | x)$
- Classification: find class labels  $\omega$  given object  $x$   
fit model using dataset  $\{x_i, \omega_i\}$   $p(\omega | x)$
- Regression: find target  $y$  given object  $x$   
fit model using dataset  $\{x_i, y_i\}$   $p(y | x)$

# Machine learning pipeline



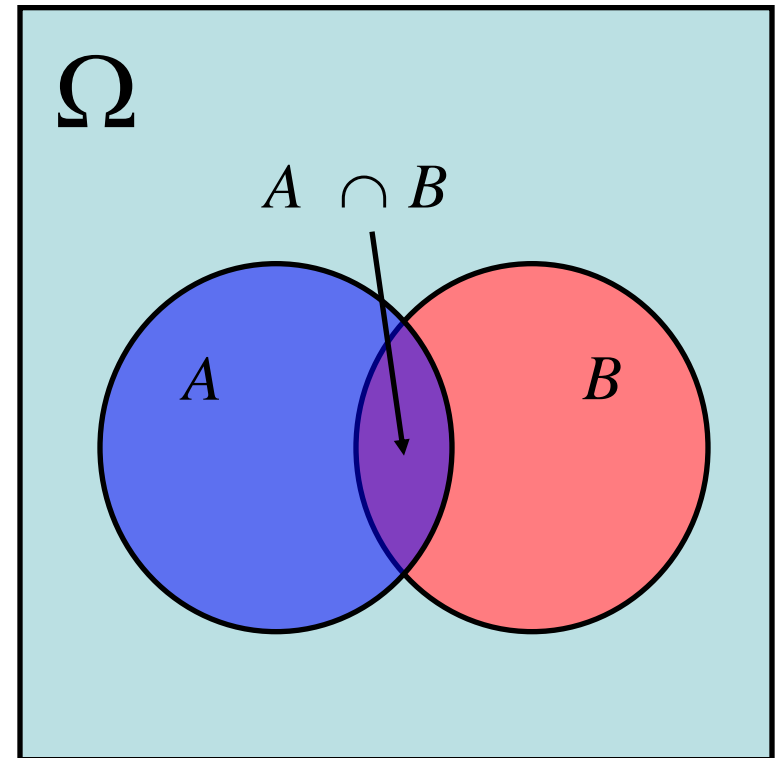
# Statistics

# Required background

- The course is aimed at PhD students with a background in bioinformatics, systems biology, computer science or a related field, and life sciences. A working knowledge of basic statistics and linear algebra is assumed.
- Self-assessment; if you have problems, read the primers
- Now, a brief recap

# Recall: probability

- $\Omega$  : all possible outcomes (sample space)  
e.g. the number of eyes on a dice: 1, 2, 3, 4, 5, 6
- $A \in \Omega$  : event  
e.g. “throwing a 3”
- $P$  : probability measure
  - $0 \leq P(A) \leq 1$
  - $P(\Omega) = 1$
  - $P(A \cup B) = P(A) + P(B) - P(A \cap B)$
  - E.g.  $P(A) = 1/6$



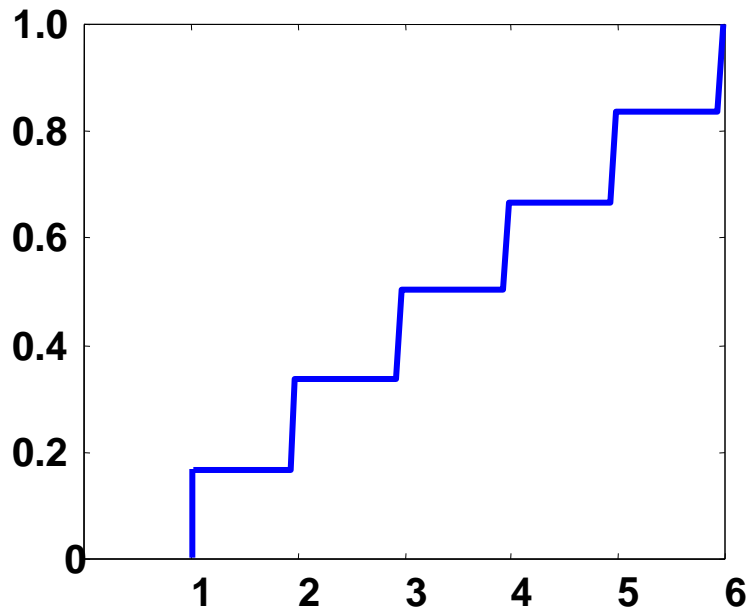
# Recall: probability (3)

- Subjective approach:  
“the probability of  $A$  is a number between 0 and 1 indicating how likely people believe  $A$  to be true”
- Frequentist approach:  
“the probability of  $A$  is a number between 0 and 1 indicating the average ratio of  $A$  being true in a large number of repeated experiments”
- Is really a philosophical debate...  
the “right” approach depends on the problem and the data available

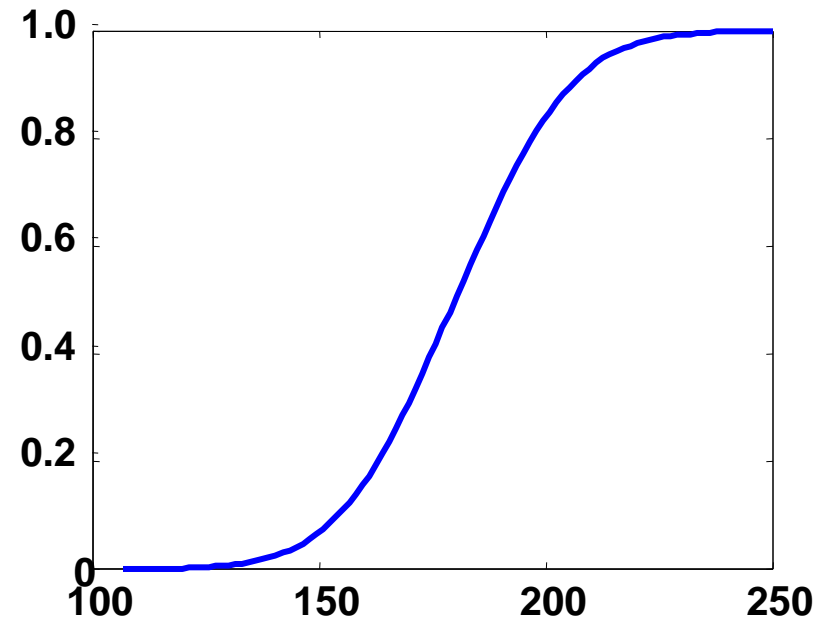
*problems (can) arise in interpretation: what does it mean?*

# Recall: CDFs

- Cumulative distribution function
- $P_X(x) = F(x)$  : probability that  $X \leq x$ ,  $\mathcal{R} \rightarrow [0,1]$



e.g. 10,000 dice throws



10,000 body lengths

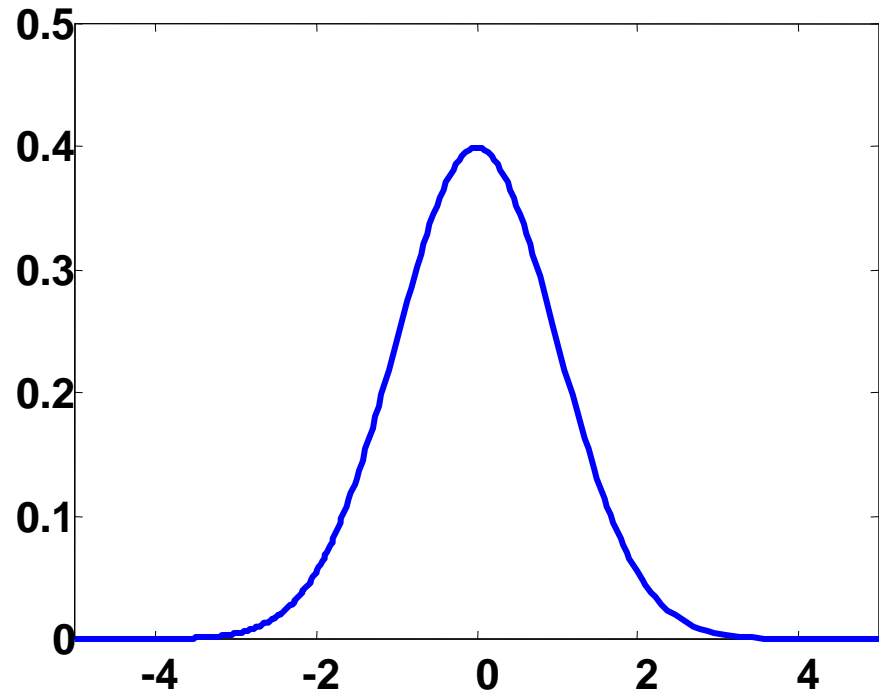
# Recall: PDFs

- $p(x) = \frac{dP(x)}{dx}$  : probability density function

- $p(x) \geq 0$

- $\int_{-\infty}^{\infty} p(x)dx = 1$

- $\int_a^b p(x)dx =$   
 $P(a \leq x \leq b)$



- **$p(x)$  is not the probability of  $X$  being  $x$  !**

# Recall: expectation

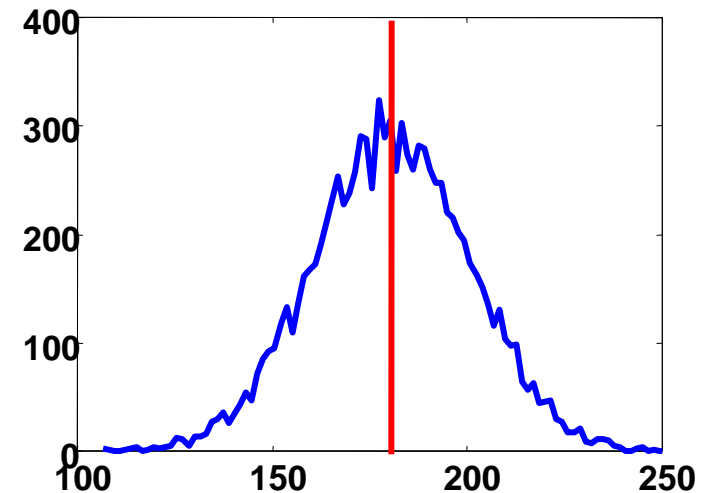
- Expectation: mean of distribution,

$$\mu = E[X] = \int_{-\infty}^{\infty} x \, p(x) \, dx$$

- Note: expectations are over entire distributions; on data sets  $\{x\}$  we can only estimate the mean,

$$m = \hat{\mu} = \frac{1}{N} \sum_{i=1}^N x_i$$

- $E[c] = c$
- $E[aX + bY] = a E[X] + b E[Y]$



*Important to realize that estimates are always based on a finite dataset!  
 $m$  is an estimate(!) of  $\mu$ ; that is why there is a hat!*

# Recall: variance

- Variance: average deviation from expected value,

$$\sigma^2 = \text{var}(X) = \int_{-\infty}^{\infty} (x - \mu)^2 p(x) dx$$

or

$$\sigma^2 = E[(X - E(X))^2] = E[X^2] - (E[X])^2$$

- $\sigma$  is called the standard deviation
- $\text{var}(X) \geq 0$
- $\text{var}(c) = 0$
- $\text{var}(aX) = a^2 \text{var}(X)$

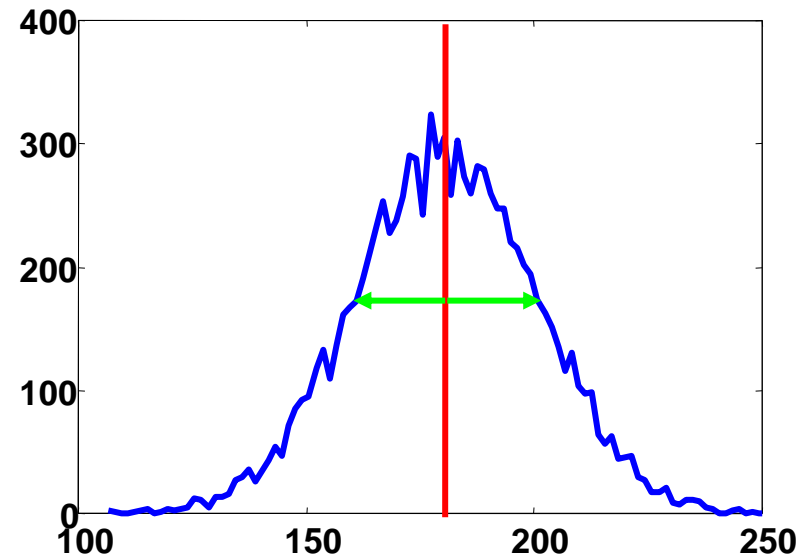
## Recall: variance (2)

- Again, on data sets  $\{x\}$  we can only estimate the variance:

$$s^2 = \hat{\sigma}^2 = \frac{1}{N} \sum_{i=1}^N (x_i - \hat{\mu})^2$$

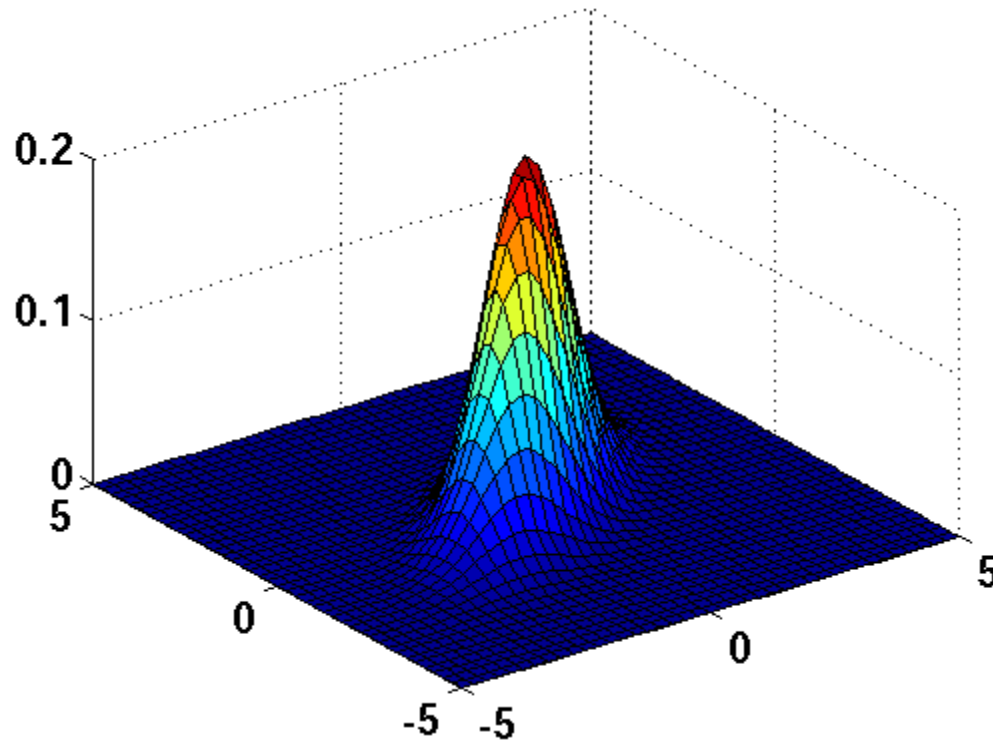
- Usually, this unbiased estimator is used:

$$s^2 = \hat{\sigma}^2 = \frac{1}{N-1} \sum_{i=1}^N (x_i - \hat{\mu})^2$$



# Recall: joint distributions

- For  $p > 1$  measurements  $x = (x_1, \dots, x_p)$ , joint distributions & densities:



# Recall: covariance

- Covariance: measure of how two random variables vary together,

$$\begin{aligned}\text{cov}(X, Y) &= E[(X - E(X))(Y - E(Y))] \\ &= E[XY] - E[X]E[Y]\end{aligned}$$

- Correlation: normalised covariance,

$$\rho(X, Y) = \frac{\text{cov}(X, Y)}{\sqrt{\text{var}(X)\text{var}(Y)}} \in [-1, 1]$$

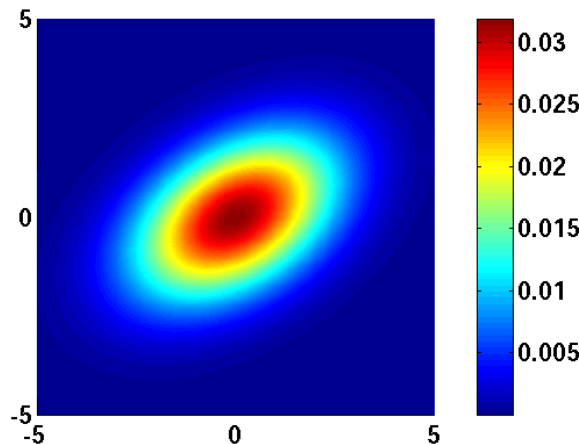
- $\text{cov}(X, Y) = 0$  :  $X$  and  $Y$  are uncorrelated

## Recall: covariance (2)

- For a set of random variables  $X_1 \dots X_p$ , we can calculate a covariance matrix,

$$\Sigma = \begin{bmatrix} \text{cov}(X_1, X_1) & \text{cov}(X_1, X_2) & \dots & \text{cov}(X_1, X_p) \\ \text{cov}(X_2, X_1) & \dots & \dots & \text{cov}(X_2, X_p) \\ \dots & \dots & \dots & \dots \\ \text{cov}(X_p, X_1) & \text{cov}(X_p, X_2) & \dots & \text{cov}(X_p, X_p) \end{bmatrix}$$

e.g.

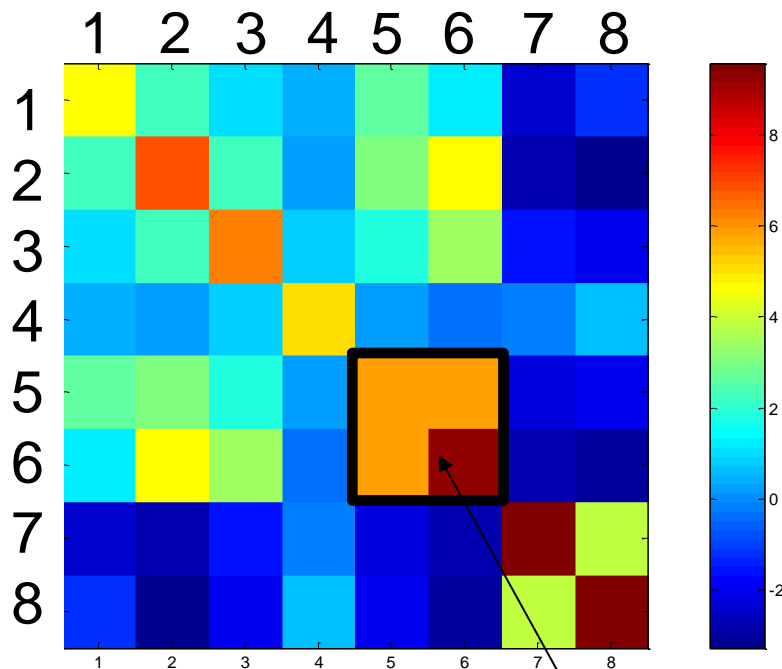


$$\longrightarrow \Sigma = \begin{bmatrix} 3 & 1 \\ 1 & 2 \end{bmatrix}$$

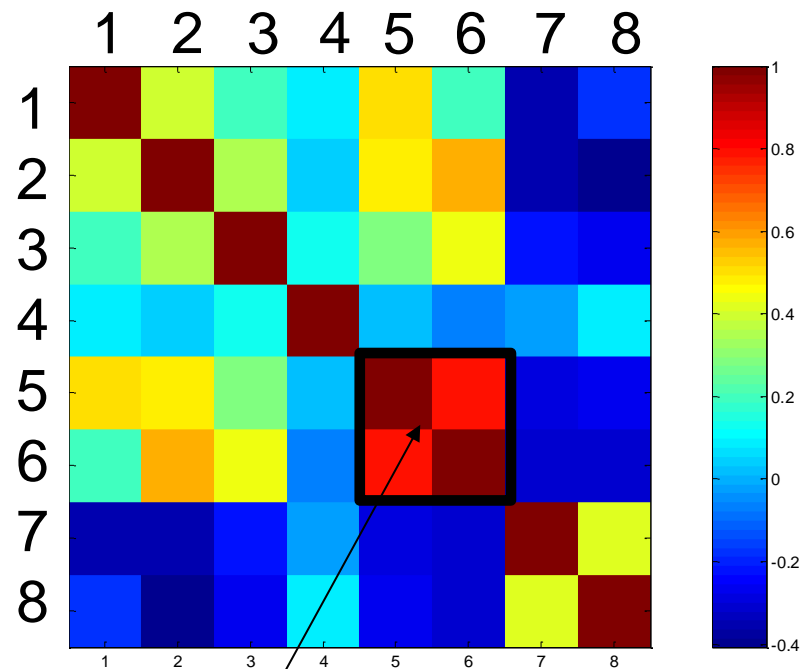
*Pairwise covariance of all features!*

# Recall: covariance (3)

- Example: IMOX data (images of handwritten digits 1:8)



`imagesc(cov(+a))`

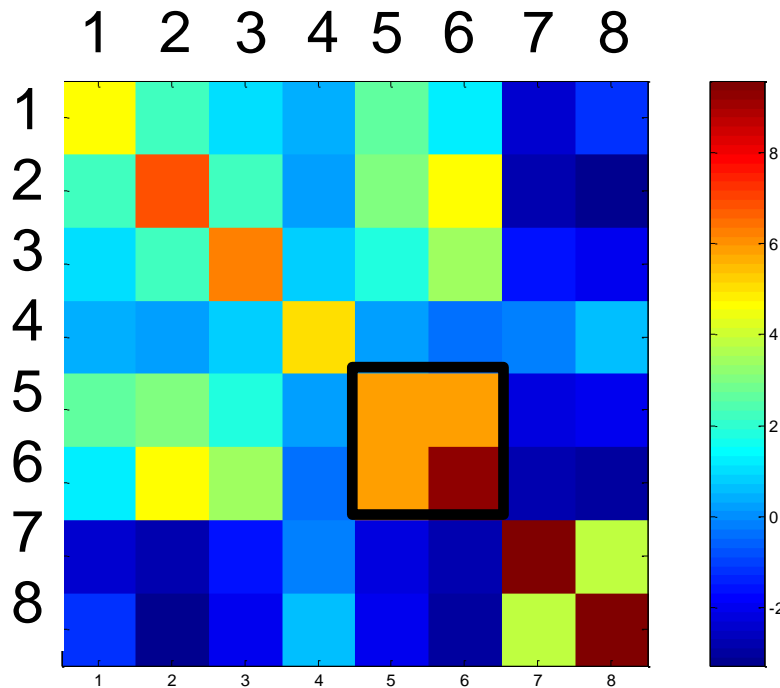


`imagesc(corrcoef(+a))`

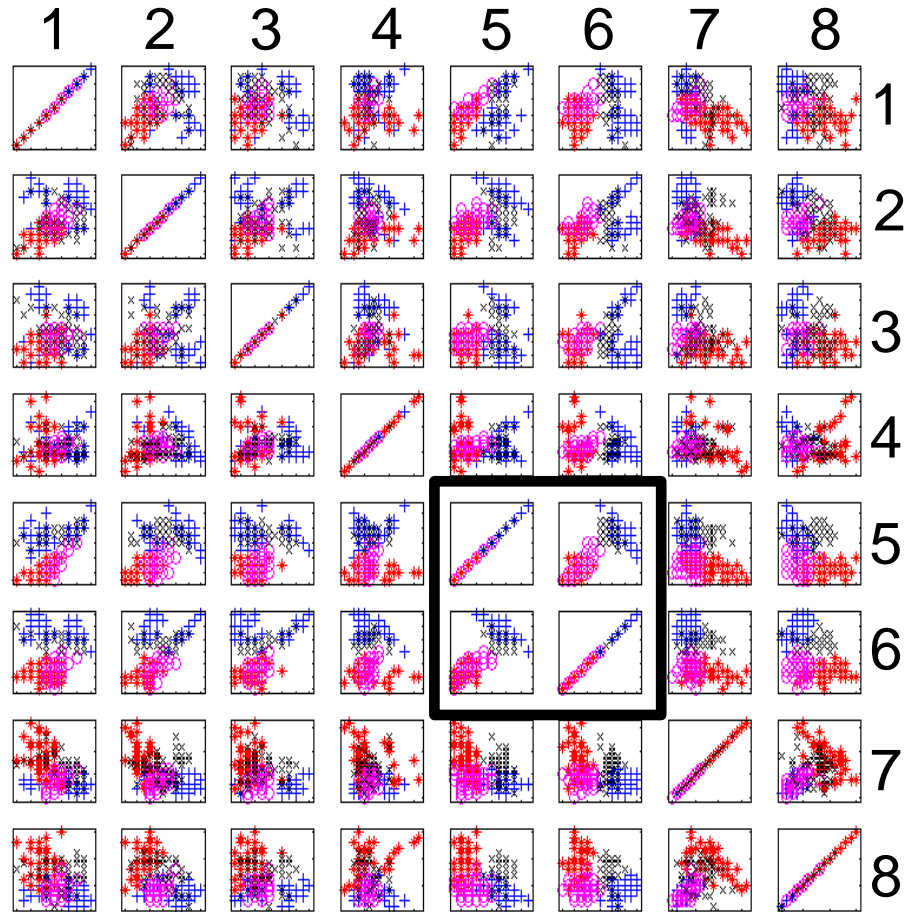
characters 5/6 are alike

# Recall: covariance (4)

- Example: IMOX data



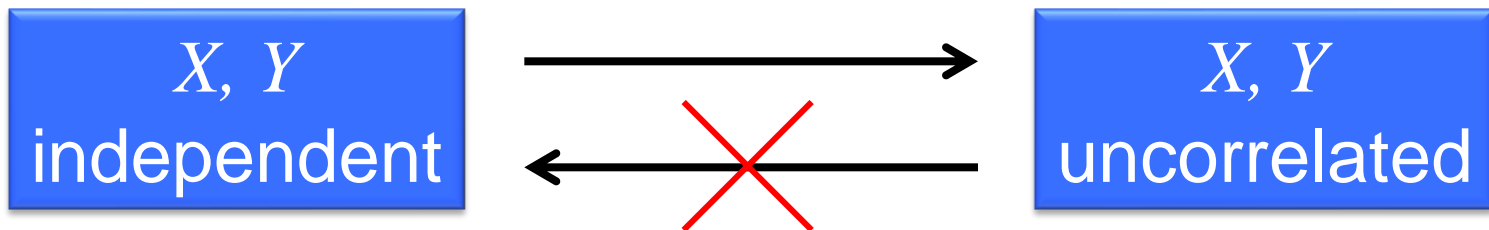
`imagesc(cov(+a))`



`scatterd(a, 'gridded')`

# Recall: independence

- Important concept: often needed as assumption!
- Two events  $A$  and  $B$  are independent iff
$$P(A \cap B) = P(A) P(B)$$
- Two random variables  $X$  and  $Y$  are independent iff
$$p(x,y) = p(x) p(y)$$



- Uncorrelated: “there’s no *linear* dependence”  
Independent: “there’s no dependence at all”

# Recall: Bayes' theorem

- Conditional probability of  $A$  given  $B$ ,

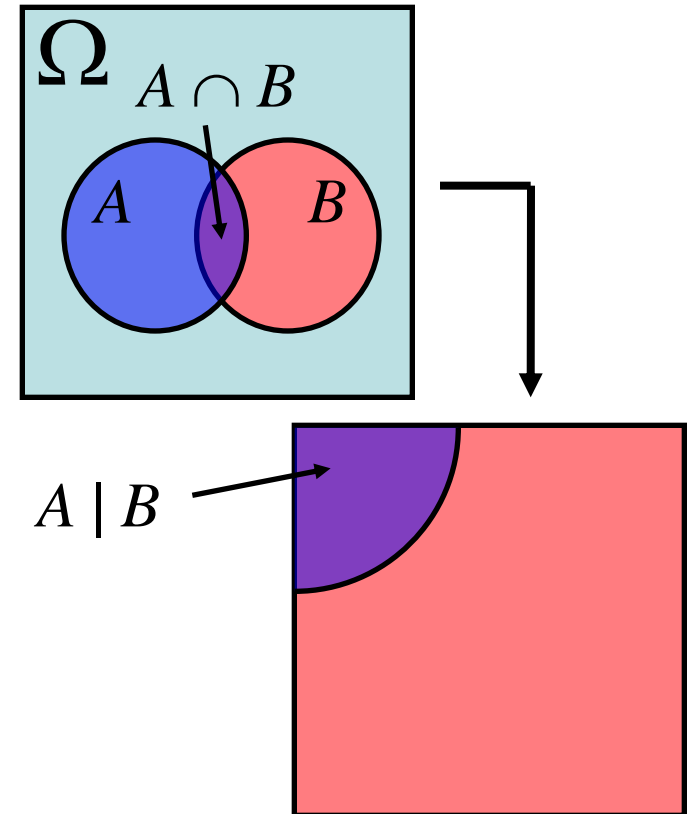
$$P(A | B) = \frac{P(A \cap B)}{P(B)}$$

- As a consequence,

$$\begin{aligned} P(A \cap B) &= P(A | B)P(B) \\ &= P(B | A)P(A) \end{aligned}$$

- Bayes' theorem:

$$P(A | B) = \frac{P(B | A)P(A)}{P(B)}$$



# Bayes' theorem (2)

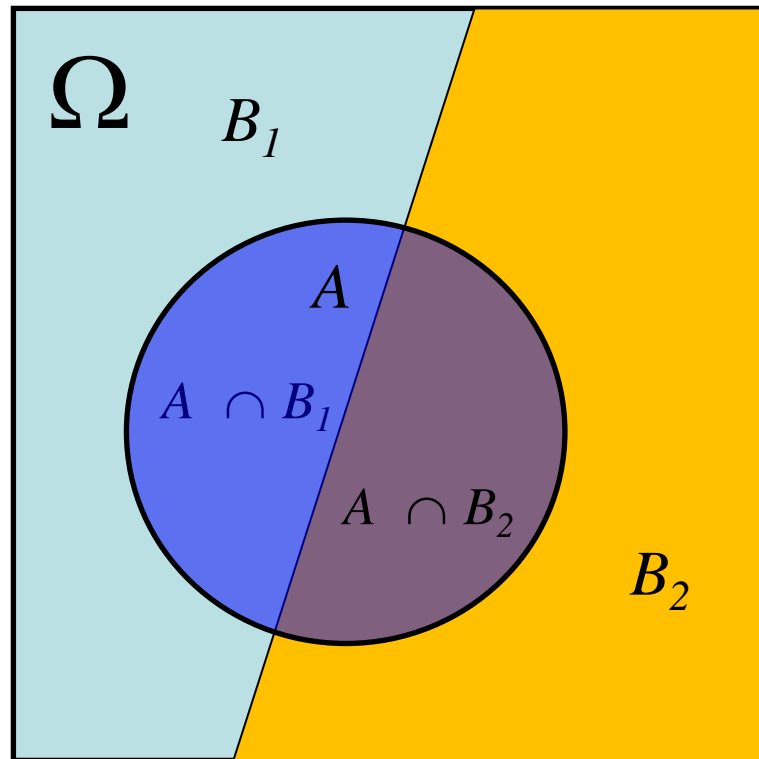
- Bayes' theorem is very useful, but controversial:
  - reverses causality
  - introduces subjective (prior) probabilities

$$P(\textit{cause} \mid \textit{effect}) = \frac{P(\textit{effect} \mid \textit{cause})P(\textit{cause})}{P(\textit{effect})}$$

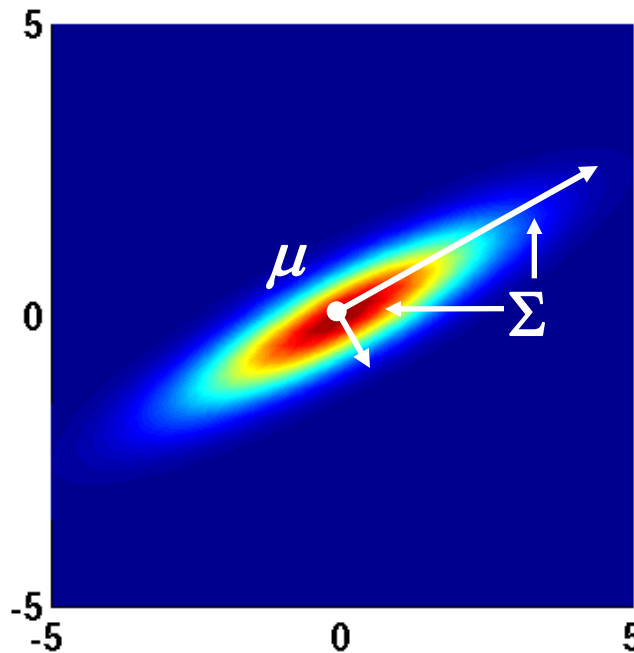
- ... but the cornerstone of pattern recognition and machine learning
  - $P(\textit{disease} \mid \textit{temperature}) = \frac{P(\textit{temperature} \mid \textit{disease})P(\textit{disease})}{P(\textit{temperature})}$
  - What is P (disease)? How to measure / know?

# Recall: total probability

- Total probability:
- $P(A) = \sum_{\forall B_i} P(A \cap B_i)$
- $P(A) = \sum_{\forall B_i} P(A|B_i)P(B_i)$



# Multivariate Gaussian distribution



$$\Sigma = \begin{bmatrix} 3 & 1\frac{1}{2} \\ 1\frac{1}{2} & 2 \end{bmatrix}$$

- $p$  - dimensional density:

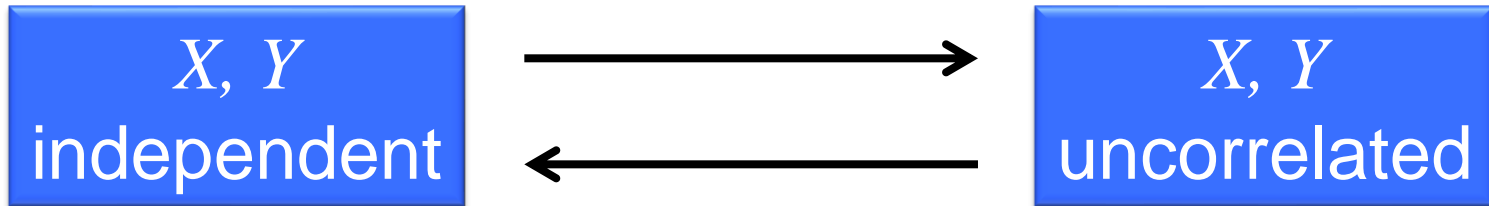
$$p(\mathbf{x}) = \frac{1}{\sqrt{2\pi^p \det(\Sigma)}} \exp\left(-\frac{1}{2}(\mathbf{x} - \boldsymbol{\mu})^T \Sigma^{-1}(\mathbf{x} - \boldsymbol{\mu})\right)$$

$\boldsymbol{\mu}$  : mean

$\Sigma$  : covariance matrix

# Special properties

- The Gaussian distribution is a special case:

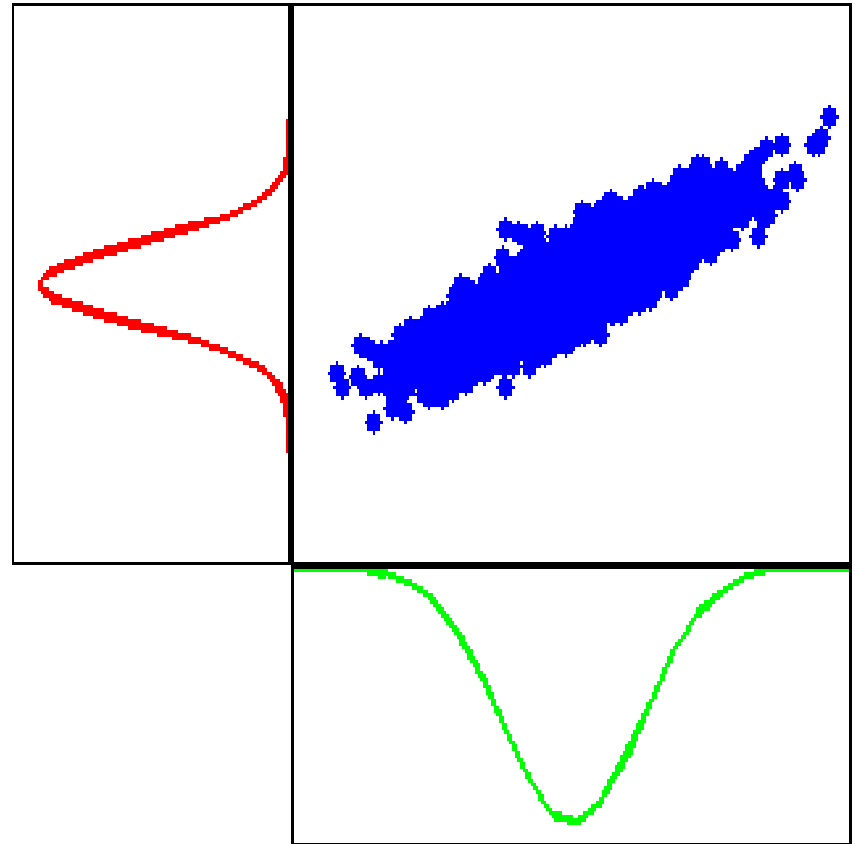


- Proof: if uncorrelated,  $\Sigma$  is diagonal ( $\sigma_1 \dots \sigma_p$ )

$$\begin{aligned} p(\mathbf{x}) &= \frac{1}{\sqrt{2\pi^p \det(\Sigma)}} \exp\left(-\frac{1}{2}(\mathbf{x} - \boldsymbol{\mu})^T \Sigma^{-1}(\mathbf{x} - \boldsymbol{\mu})\right) \\ &= \frac{1}{\sqrt{2\pi\sigma_1^2}} \exp\left(-\frac{1}{2}(x_1 - \mu_1)^T \sigma_1^{-2}(x_1 - \mu_1)\right) \times \frac{1}{\sqrt{2\pi\sigma_2^2}} \exp\left(-\frac{1}{2}(x_2 - \mu_2)^T \sigma_2^{-2}(x_2 - \mu_2)\right) \\ &\quad \times \dots \times \frac{1}{\sqrt{2\pi\sigma_p^2}} \exp\left(-\frac{1}{2}(x_p - \mu_p)^T \sigma_p^{-2}(x_p - \mu_p)\right) = p(x_1)p(x_2)\dots p(x_p) \end{aligned}$$

## Special properties (2)

- Any projection of a high-dimensional Gaussian is itself again Gaussian

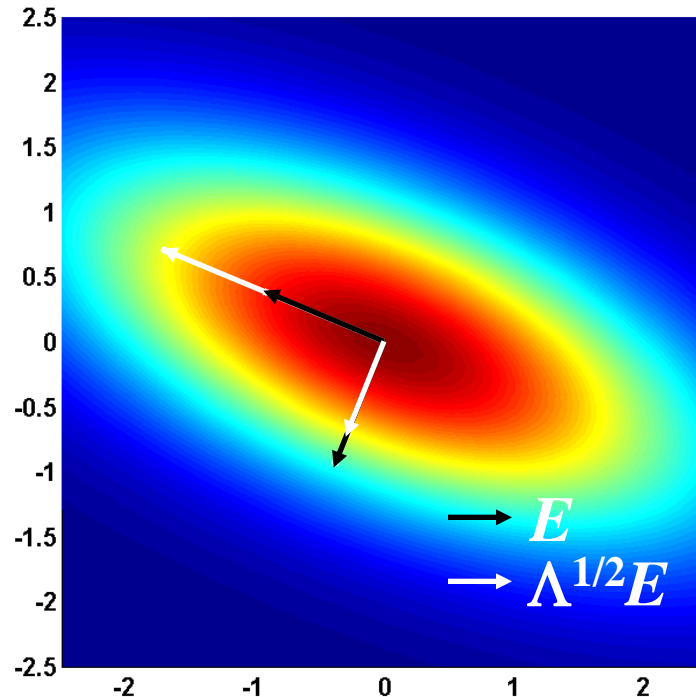


# Sphering

- **Eigenanalysis** on a  $p \times p$  covariance matrix  $\Sigma$  :  
solve for  $i = 1, \dots, p$ 
  1.  $\det (\Sigma - \lambda_i \mathbf{I}) = 0$
  2.  $(\Sigma - \lambda_i \mathbf{I}) \mathbf{e}_i = 0$
- $\Sigma = \mathbf{E}^T \Lambda \mathbf{E}$
- The  $\mathbf{e}_i$  are the **eigenvectors**,  
stored as the columns of matrix  $\mathbf{E}$ ;  
they correspond to the main axes of the Gaussian
- The  $\lambda_i$  are the **eigenvalues**,  
stored on the diagonal of matrix  $\Lambda$ ;  
they correspond to the lengths of the main axes

## Sphering (2)

- Covariance matrix determines shape of density

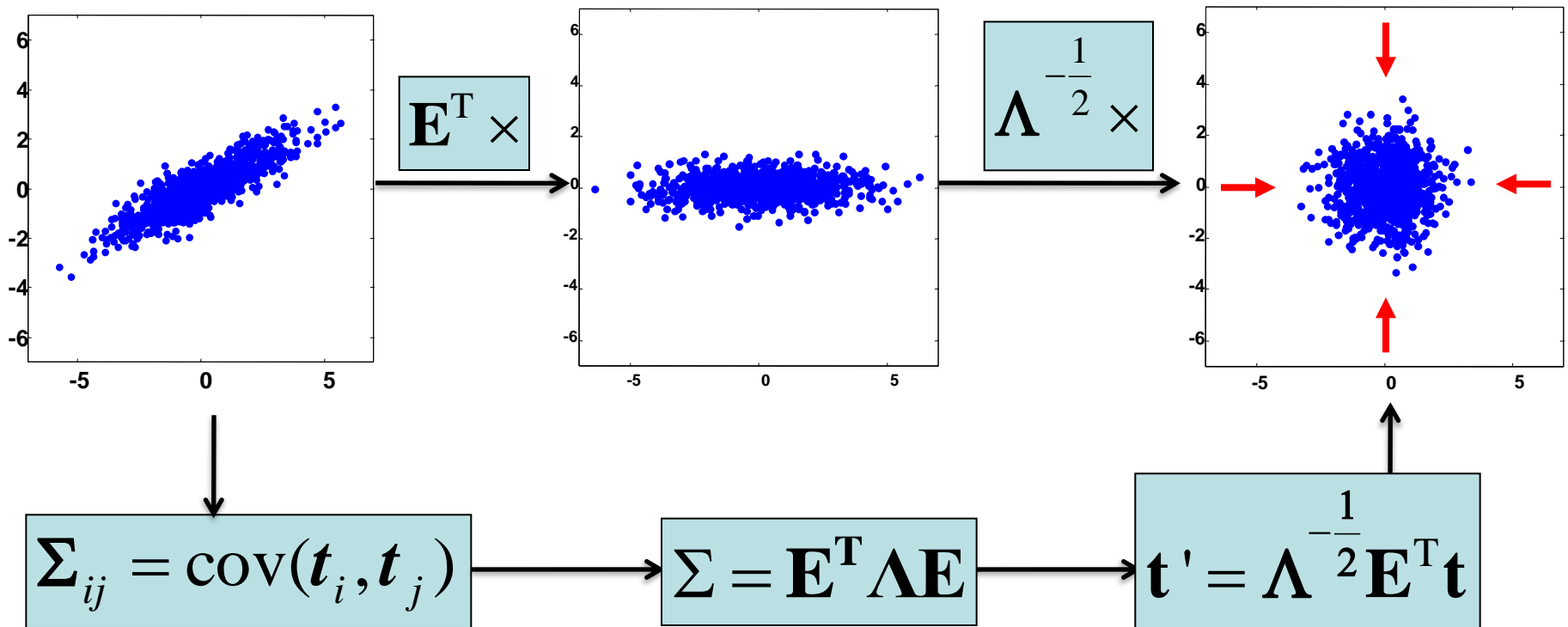


- Eigenvectors correspond to main axes of Gaussian, e.g.

$$\Sigma = \begin{bmatrix} 3 & -1 \\ -1 & 1 \end{bmatrix} \rightarrow \mathbf{E} = \begin{bmatrix} -0.92 & -0.38 \\ 0.38 & -0.92 \end{bmatrix} \quad \Lambda = \begin{bmatrix} 3.41 & 0 \\ 0 & 0.59 \end{bmatrix}$$

# Sphering (3)

- Eigenanalysis of covariance matrix can be used to “sphere” or “whiten” data:

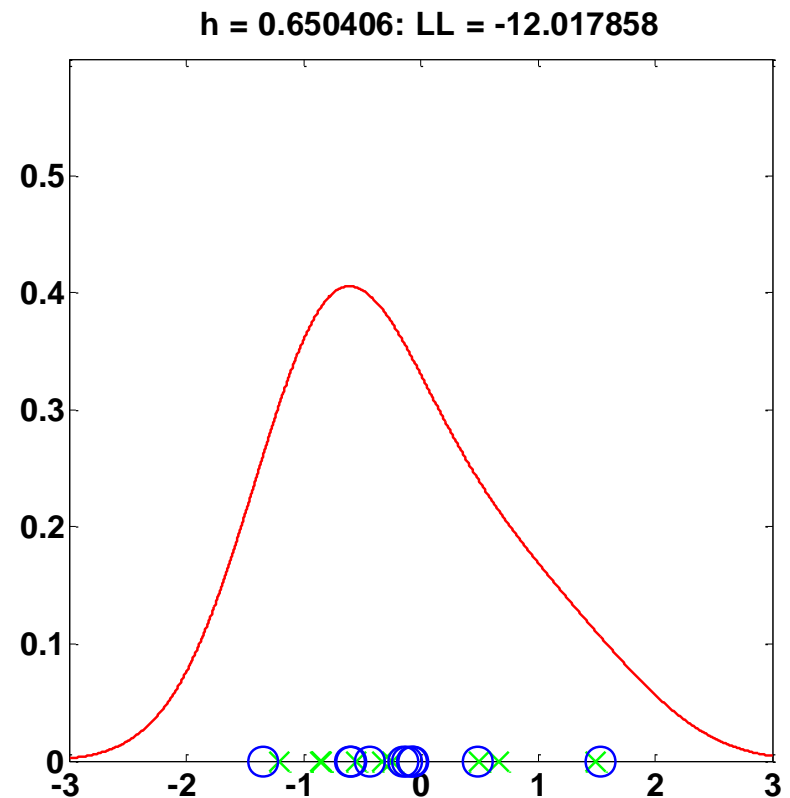


- After sphering,  $\Sigma_{ij} = \mathbf{I}$

# Cross-validation

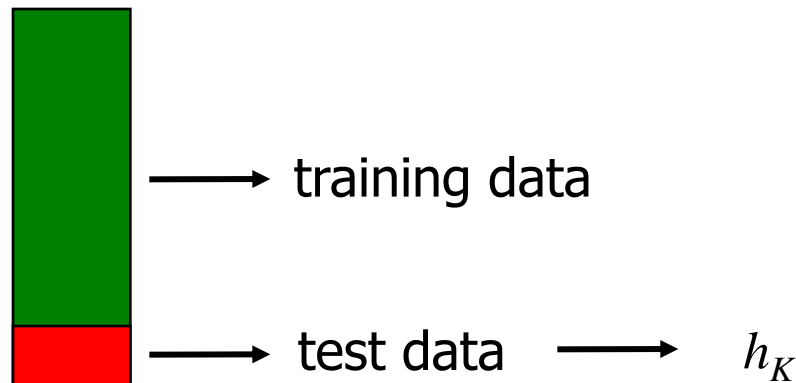
# Cross-validation

- Solution:
  - Split data into *training set* and *validation set*
  - Optimise  $h$  w.r.t. likelihood of validation set, given Parzen model trained on training set
- Problems:
  - Uses a lot of valuable data
  - Sensitive to split of data



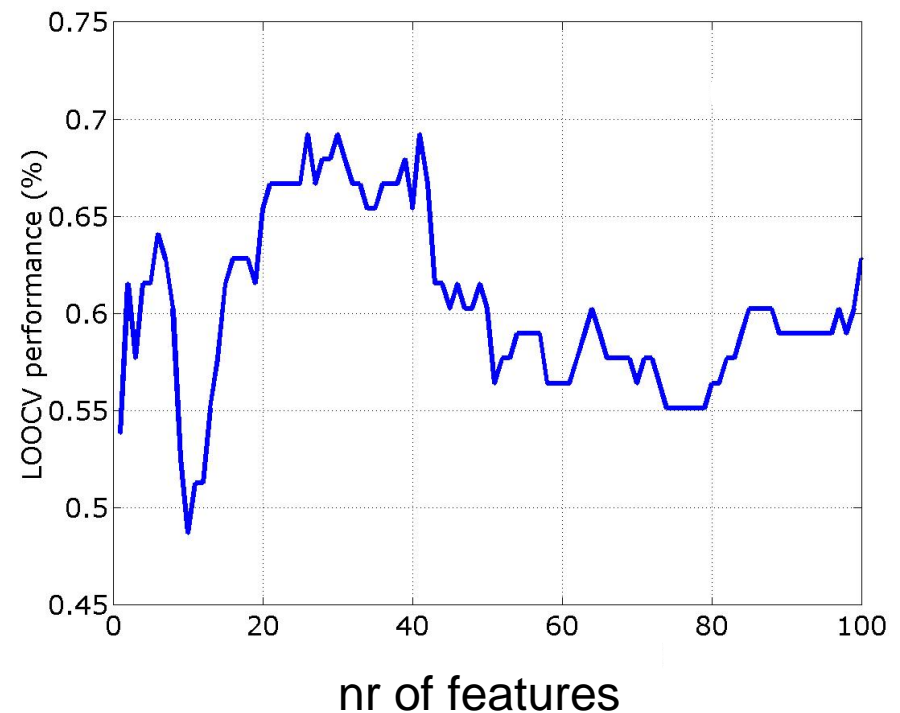
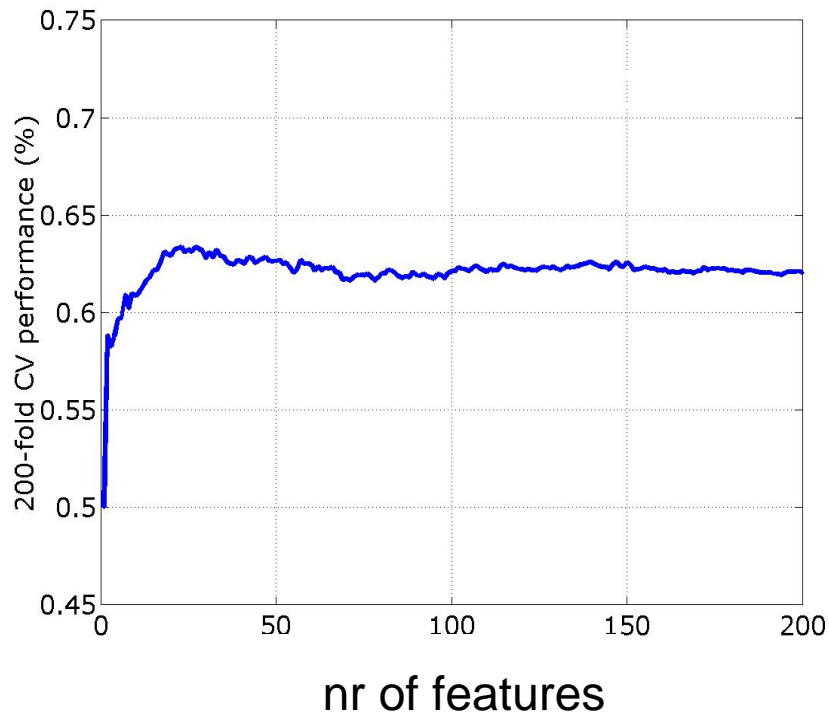
# Cross-validation (2)

- Better solution:  $K$ -fold crossvalidation
  - Split data into  $K$  parts ( $K = n$ : leave-one-out)
  - Repeat  $K$  times:
    - Find  $h$  using  $(K - 1)$  parts for training and 1 part for testing
  - Use average of  $h$ 's as kernel width



# Cross-validation (3)

- (Prefer) *K*-fold cross-validation over leave-one-out
  - Smoother (less variance) and more biased (conservative)



# Bootstrap

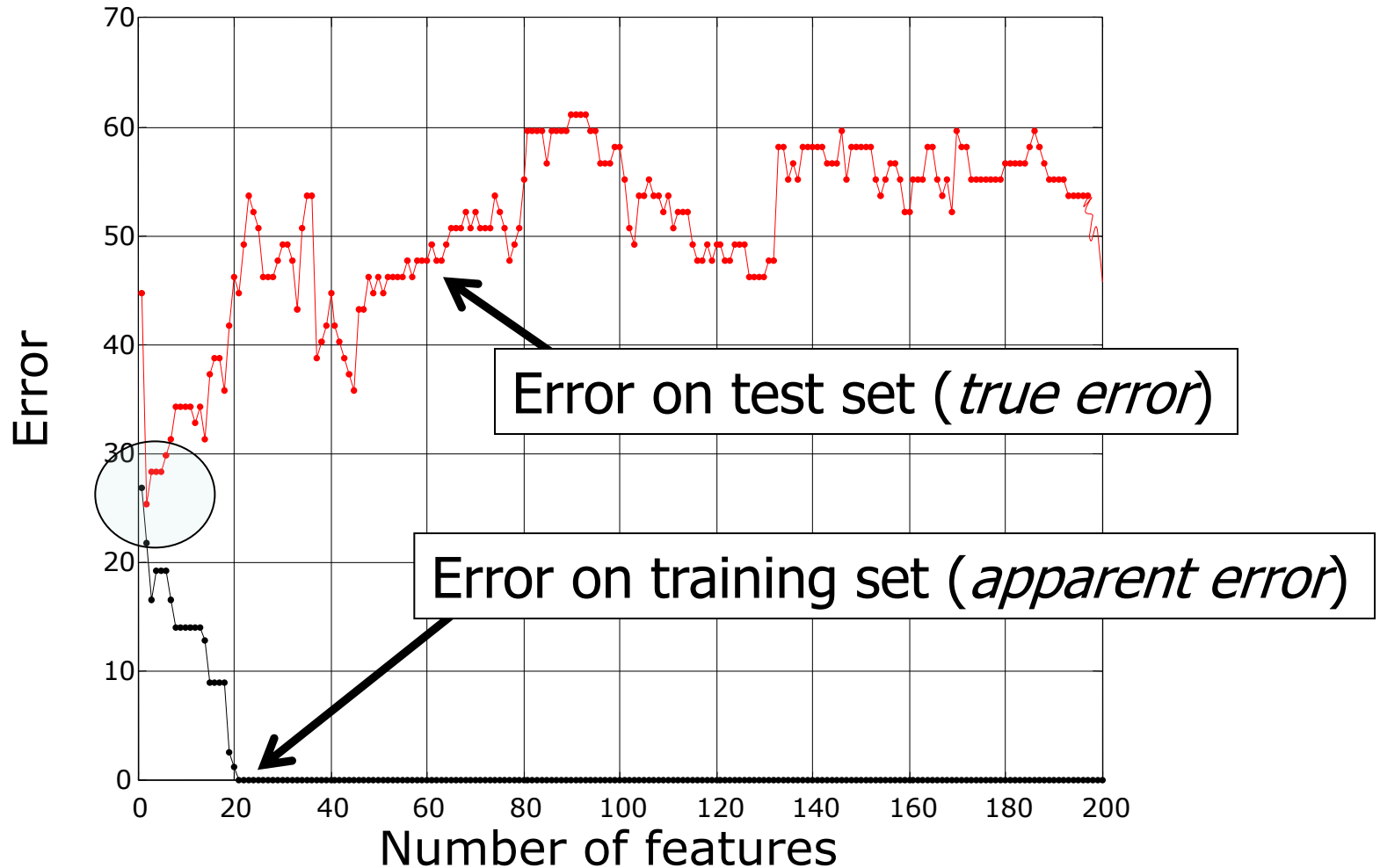
- Alternative to cross-validation:
  - Repeat  $K$  times:
    - Draw  $n$  objects from the dataset, **with replacement** (some objects will be selected more than once)
    - Test using objects that were not selected
- Cross-validation and bootstrap estimates are *biased*
  - They are conservative (i.e. too pessimistic) because they do not use all data available

*You want to get an estimate when you fit on complete/all data. CV/Bootstrap are thus biased wrt fitting on complete data!*

# Training, test and validation sets

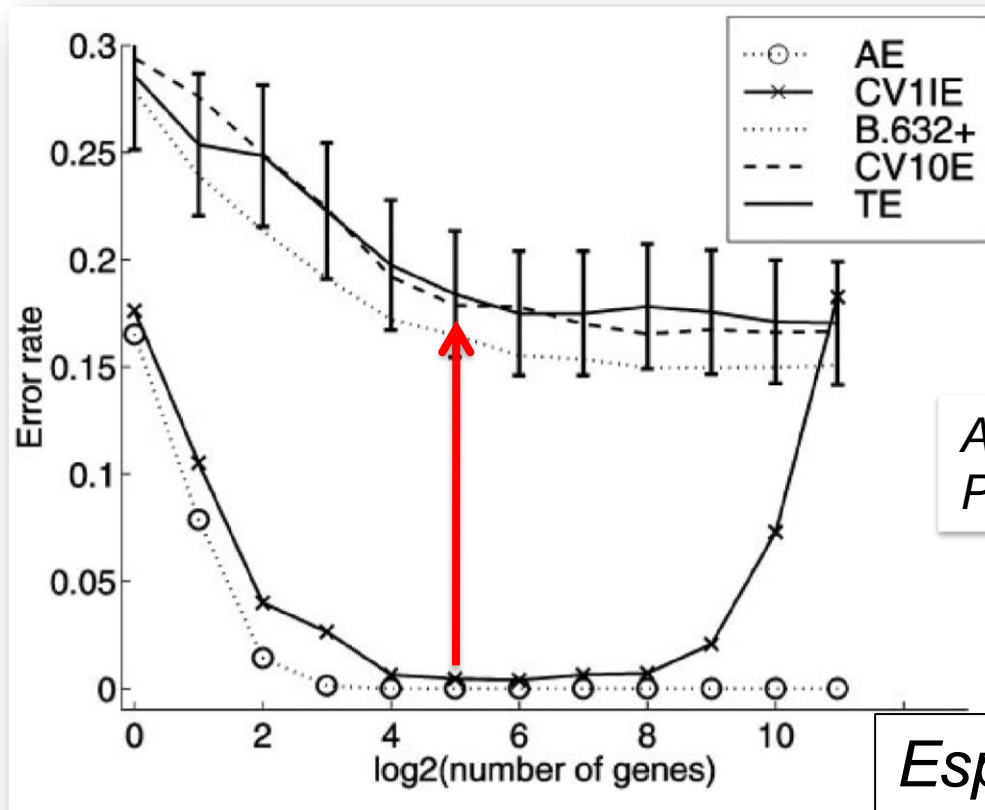
- Terminology:
  - A *training set* is used to estimate parameters
  - An optional *validation set* is used to optimize parameter settings, e.g. by calculating classifier error on this set
  - **A *test set* is only used to judge performance of the entire classifier (only used once!)**
- Error estimates:
  - On training set: *apparent error*
  - On test set: *true error*

# Training, test and validation sets (2)



# Training, test and validation sets (3)

- The test set should *never* be used to set any parameters!  
This leads to biased estimates of performance -- in practice we may do much worse than we predict



Ambroise et al.,  
PNAS 2002

*Especially in bioinformatics  
i.e.  $p \gg n$  problems*

## Training, test and validation sets (4)

